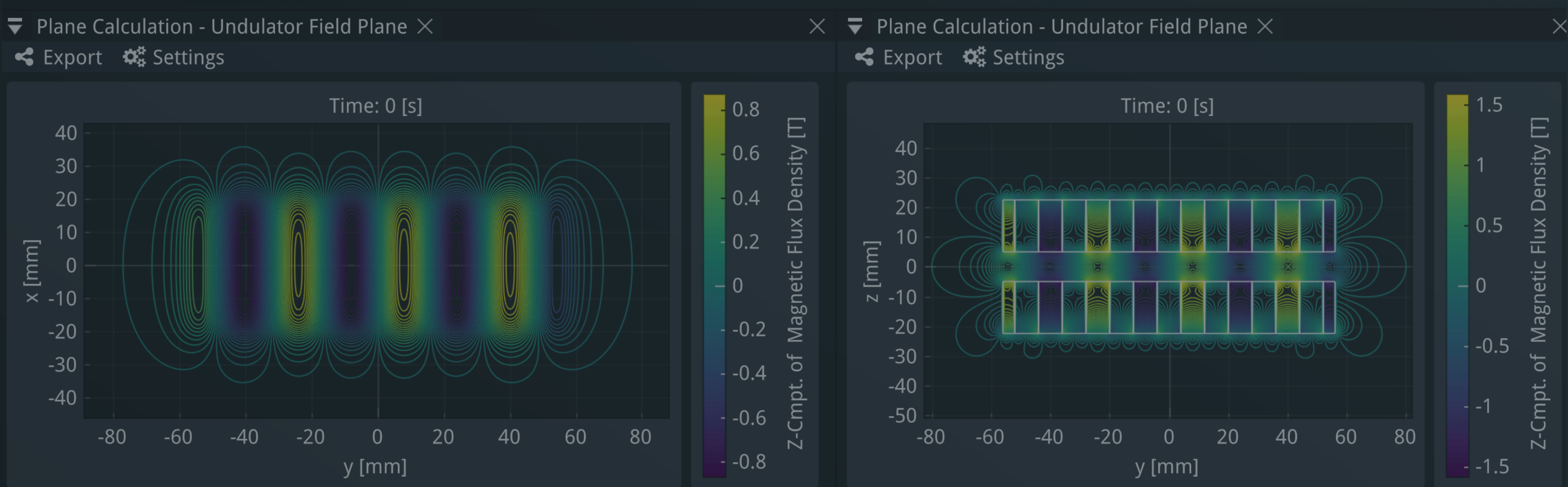


Rat

Integral Methods for Magnetostatic Simulation

```
>>>771.171
>>>11
>>>71111+87
>7C568+0000E3085C71>>
79+00000000+00000000e>>+87>
100+0000000000000000e>>
a0+0000000000000000e2>
5+0000000000000000e7>
1+0000000000000000e4>
C+0000000000000000e7>7>8C>
14+00+000000000000e7>7>
>75+00+00+00+00e67>
>>>111>>>
```

Rat-GUI
v2.022.2
J. van Nugteren





Motivation

Magnetostatic simulations for accelerator magnets and insertion devices involve:

- ▶ Open magnetic domains
- ▶ Long-range magnetic interactions
- ▶ Nonlinear ferromagnetic materials
- ▶ Permanent magnet assemblies
- ▶ Repeated optimization and field evaluation

Classical FEM approaches:

- ▶ Require meshing large surrounding air regions
- ▶ Introduce artificial outer boundaries
- ▶ Increase memory usage and nonlinear solve cost for large open-domain problems

Integral formulations:

- ▶ Only discretize magnetic regions
- ▶ Open-boundary conditions are inherently satisfied
- ▶ Naturally suited for magnetostatic field interactions

Rat combines:

Biot–Savart field evaluation with the **Multi-Level Fast Multipole Method**, a **Volume Integral Method** for non-linear materials, and **parametric magnet geometry** modelling



What is Rat?

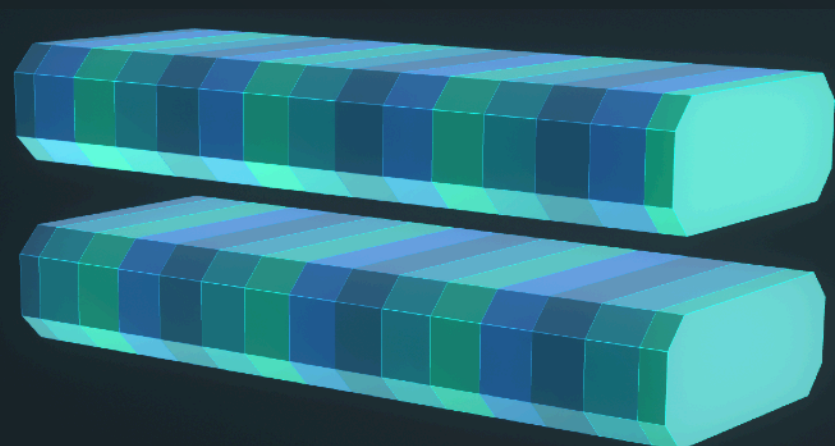
RAT is an open-source framework for 3D magnet modelling and magnetostatic simulation based on integral formulations, fast multipole acceleration, and nonlinear magnetic material models.

3D Geometry modelling

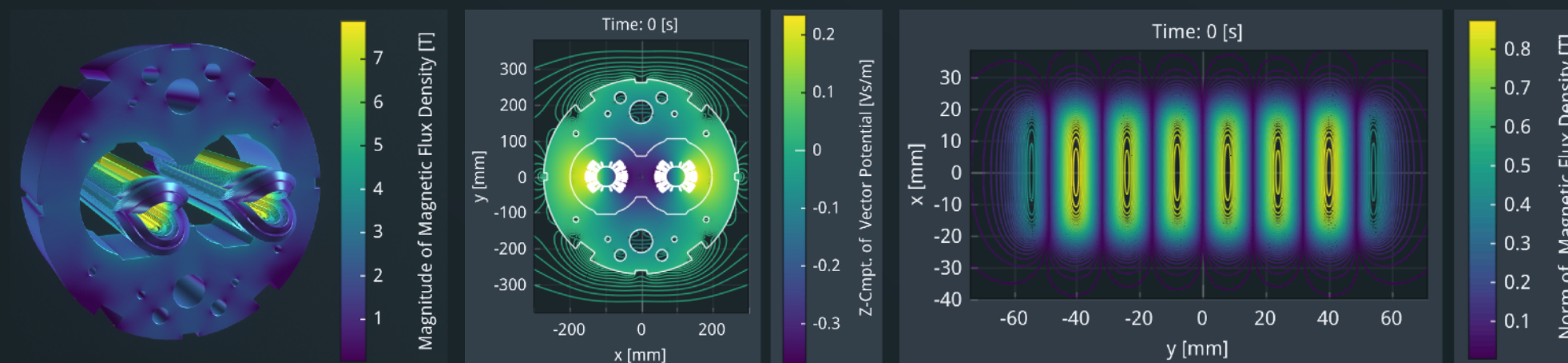
- ▶ Coil, cable, and solid geometries
- ▶ Hierarchical model construction
- ▶ Integrated post-processing tools



LHC dipole 3D



Simple undulator

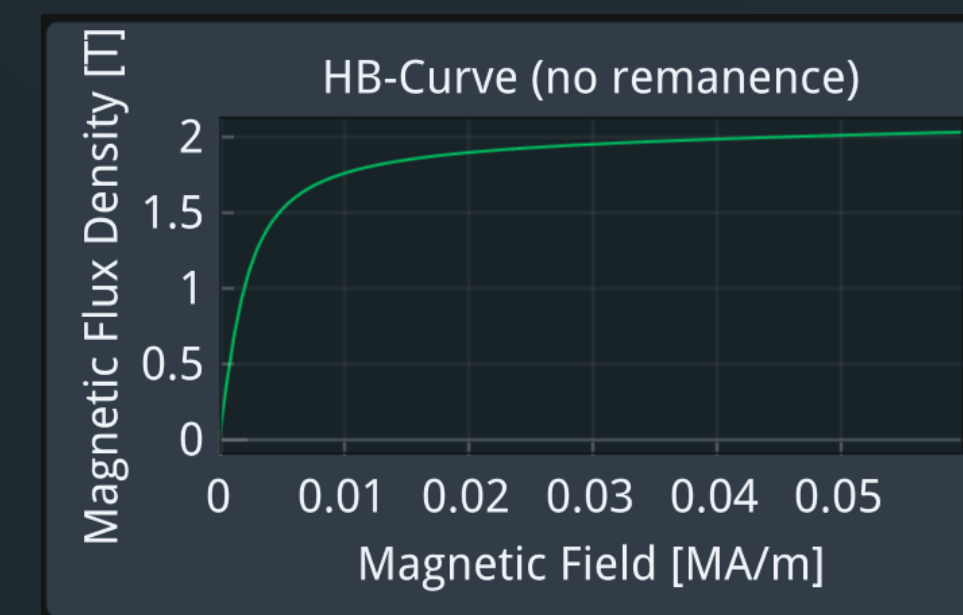


Field computation

- ▶ Biot–Savart formulation
- ▶ Multi-Level Fast Multipole Method (MLFMM)
 - ▶ Efficient long-range interaction evaluation
- ▶ GPU acceleration

Magnetic materials

- ▶ Volume Integral Method (VIM)
- ▶ Only magnetic regions discretized
- ▶ Nonlinear ferromagnetic materials
- ▶ Including permanent magnets



Applications: accelerator magnets, insertion devices, electromagnets, and permanent magnet systems



What is Rat?

Rat Library

Rat Graphical User Interface

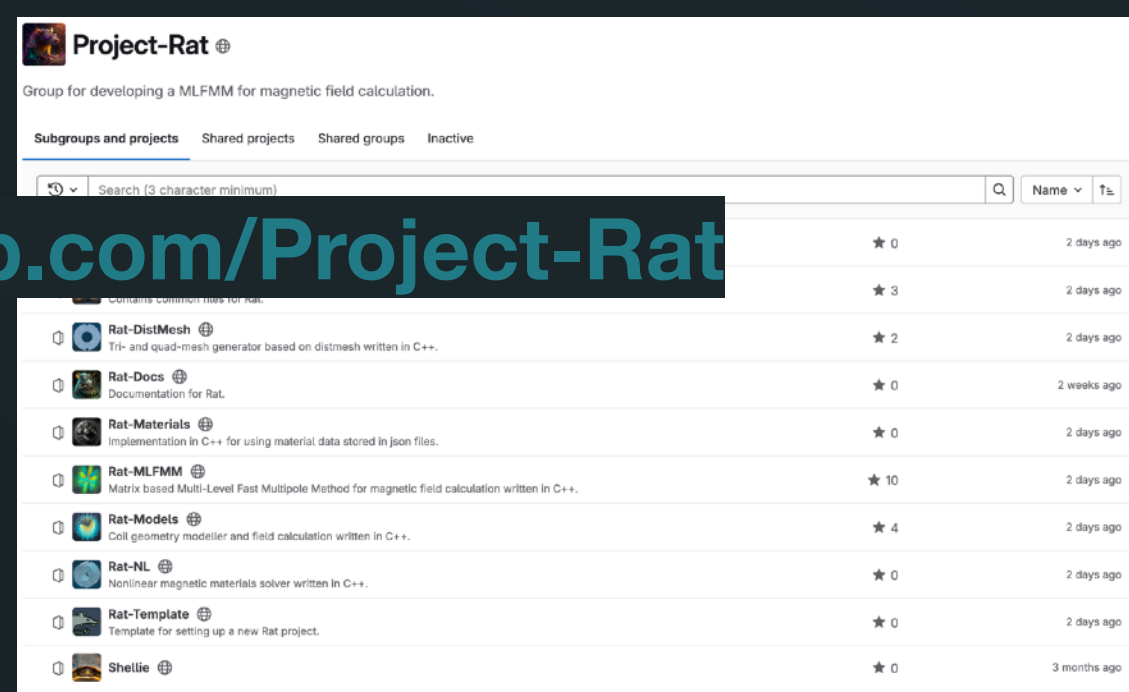
- ▶ **Open-source** modelling and simulation software for magnet engineers
- ▶ Written in modern, **object-oriented C++**
- ▶ Designed for **accurate simulations** of electromagnetic fields, inductance, quench protection, particle tracking and more

- ▶ **Modular and extensible:** build your own workflows

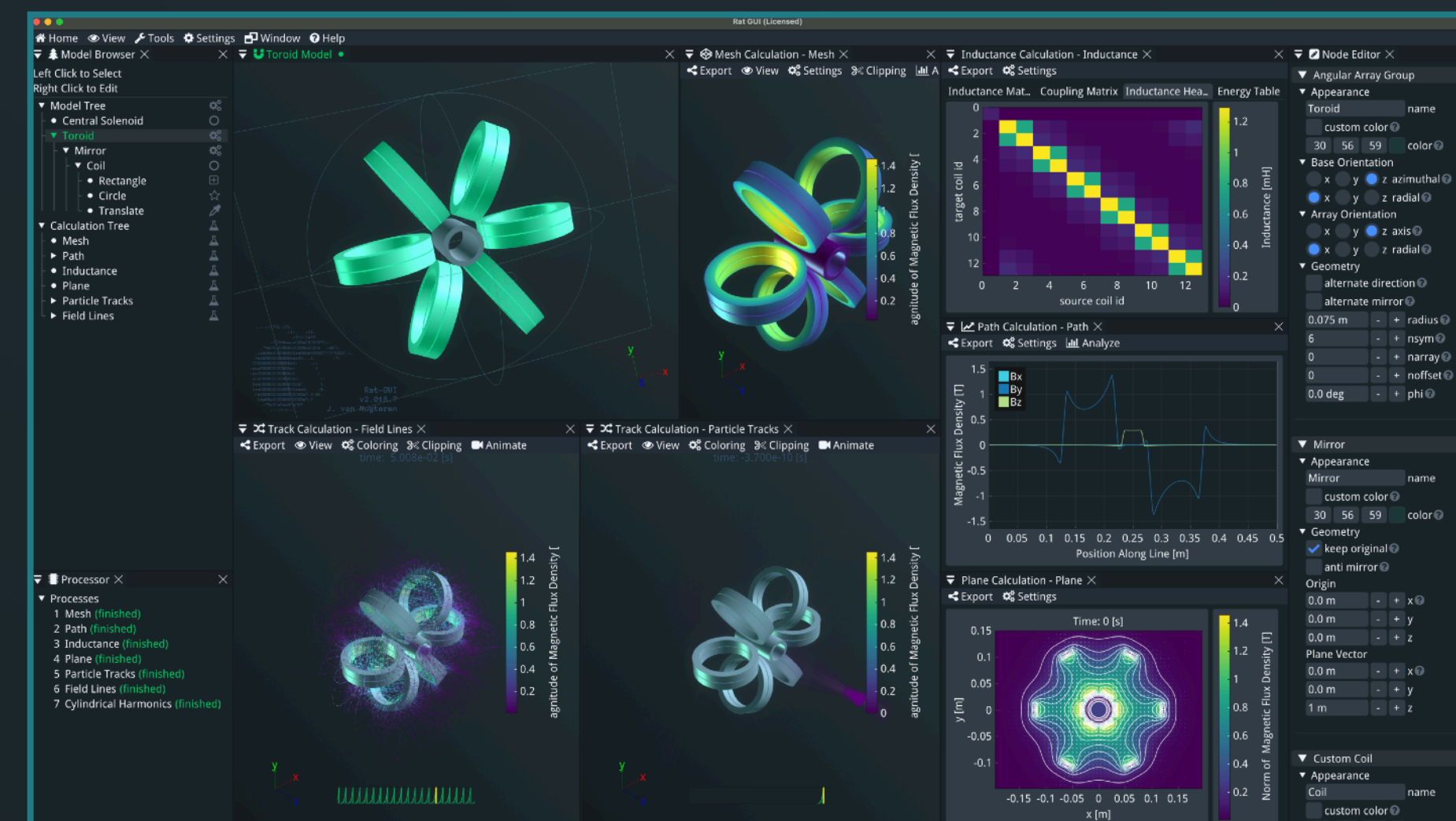
- ▶ Available on GitLab:



<https://gitlab.com/Project-Rat>

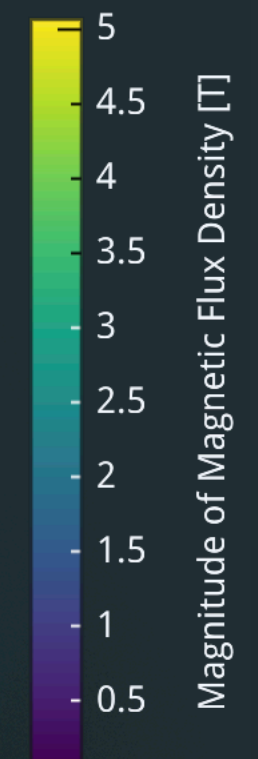
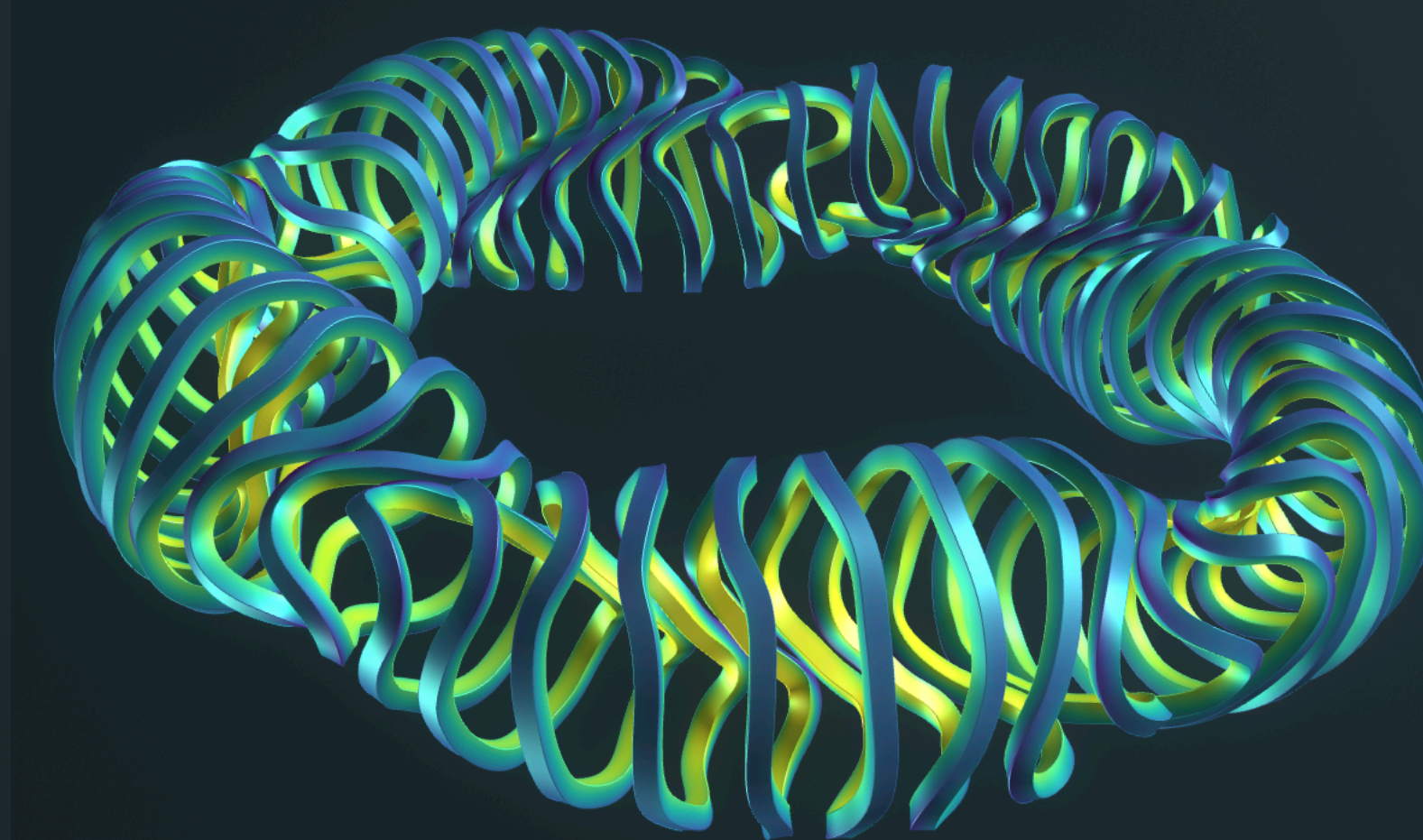
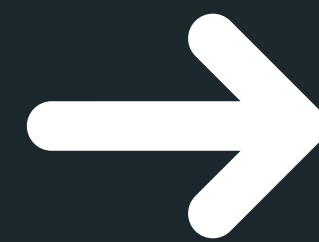
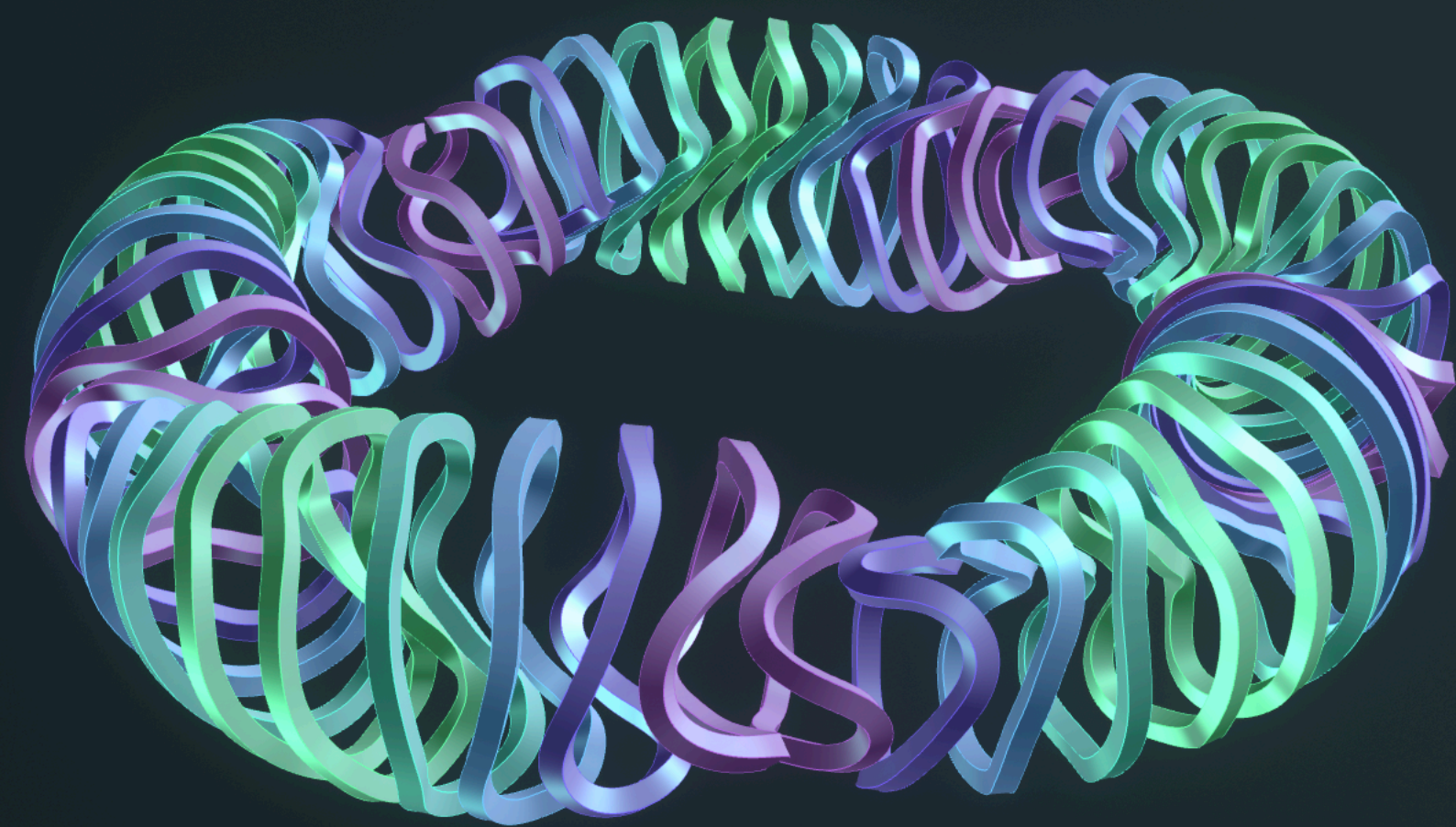


- ▶ A **user-friendly** graphical interface for Rat
- ▶ **No coding** required: full access to Rat's capabilities
- ▶ **Visual modelling** of coils, magnets, and iron structures
- ▶ Access to **all modelling and calculation tools** of the Rat library
- ▶ Same speed and accuracy, but **ultimate convenience**





Calculating Magnetic Fields With Multi-Level Fast Multipole Method

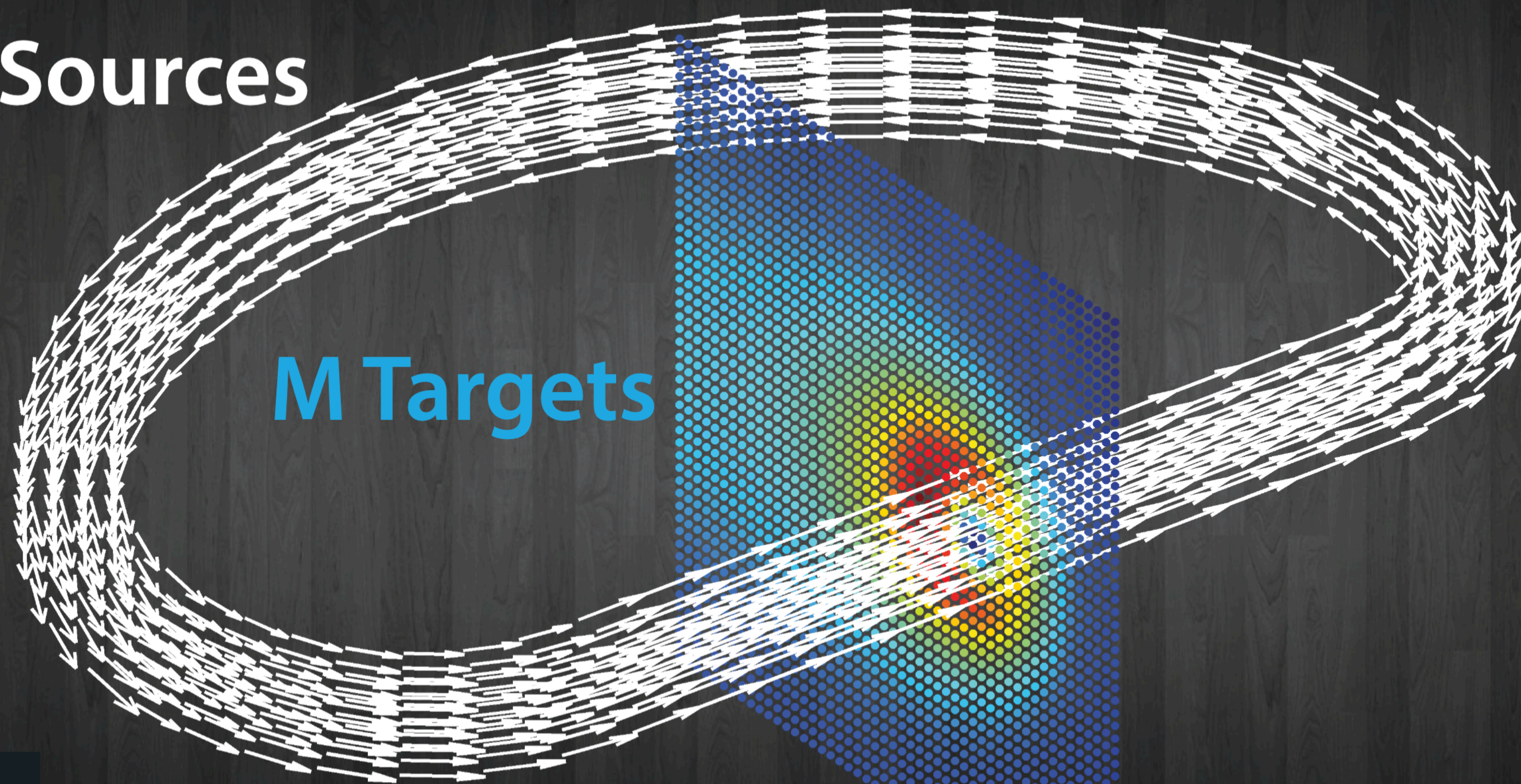




Calculating the magnetic field from a coil

N Sources

M Targets



Finite Element Method?
Direct Biot Savart $\rightarrow O(N \times M)$
MLFMM $\rightarrow O(N + M)$



Top 10 Algorithms of the 20th Century

- According to SIAM [1]

1. 1946 - Monte Carlo method
2. 1947 – Simplex method for linear programming
3. 1950 – Krylov subspace iteration methods
4. 1951 – Decompositional approach to matrix computations
5. 1957 – Fortran optimizing compiler
6. 1959 – QR algorithm
7. 1962 – Quicksort
8. 1965 – Faster Fourier Transform
9. 1977 – Integer relation detection algorithm
10. 1987 – **Fast Multipole Algorithm (FMM)**

Fathers of FMM



Leslie Greengard



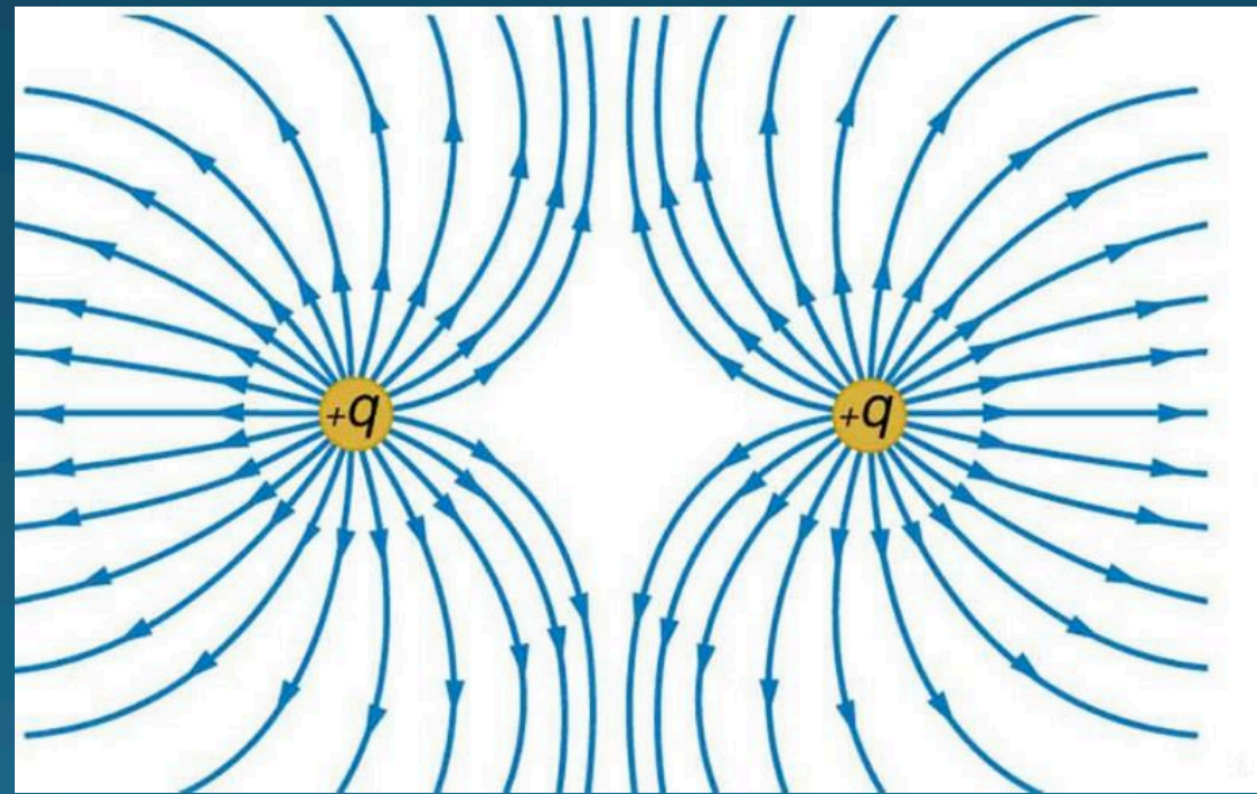
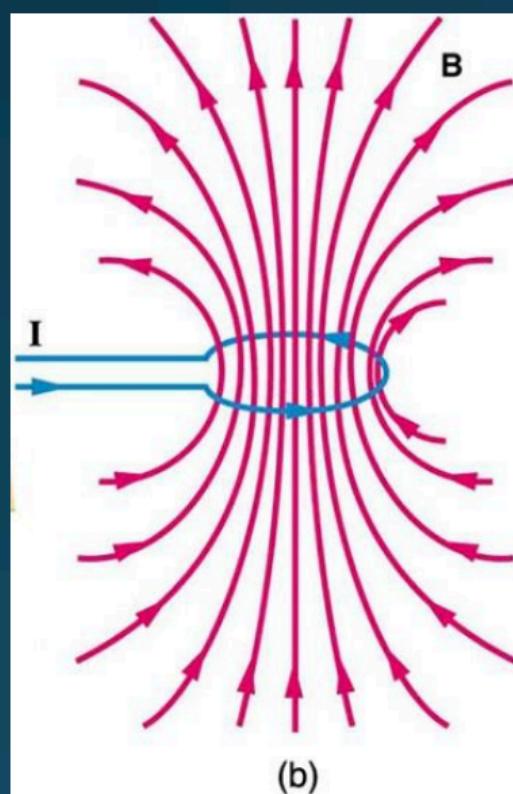
Vladimier Rokhlin

[1] Barry A. Cipra, “The Best of the 20th Century: Editors Name Top 10 Algorithms”, SIAM News, vol 33, number 4



What is so great about it?

- It can solve basically all **N-body** problems involving some form of field with **$O(N)$** complexity!
 - Electro Statics – Calculate electric potential and field from point charges
 - **Magneto-Statics** – Calculate magnetic vector potential and field from line currents/magnetic moments (**Biot Savart**)
 - Electrical Network Solver – Calculate induced voltage based on current change in all elements (**must have for NI coils**)
 - Astrophysics – Calculate gravitational potential and field
 - Plasma physics?
 - Many more. (=





Rat for Coils: Biot-Savart with MLFMM

In integral magnetostatics:

- ▶ Magnetic fields are computed from source to target interactions
- ▶ In Rat: using the vector potential version of Biot-Savart law

$$\mathbf{B}(\mathbf{r}) = \nabla \times \mathbf{A}(\mathbf{r}) = \frac{\mu_0 I}{4\pi} \oint_C \frac{d\mathbf{l}' \times \mathbf{R}}{|\mathbf{R}|^3}$$
$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0 I}{4\pi} \oint_C \frac{d\mathbf{l}'}{|\mathbf{r} - \mathbf{r}'|}$$

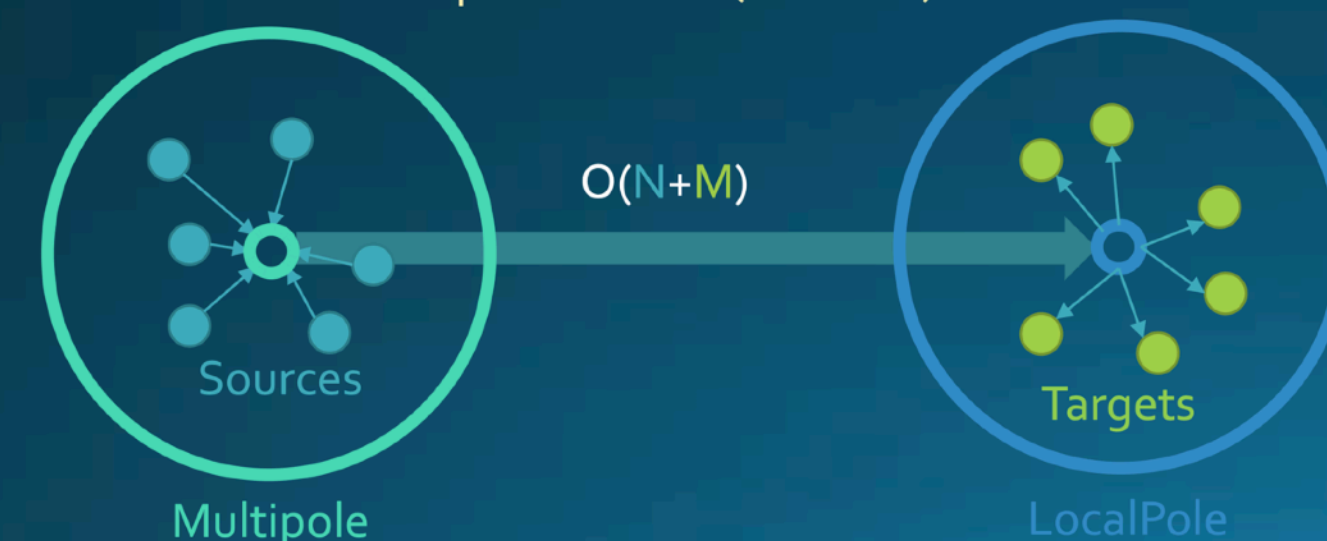
Direct interaction evaluation means:

- ▶ Every source n_i interacts with every target m_j
- ▶ Computational complexity: $O(NM)$
- ▶ Large magnet systems quickly become computationally expensive

Direct Biot Savart Method



Multi-Level Fast Multipole Method (MLFMM)



*Rat accelerates Biot-Savart integration using the **Multi-Level Fast Multipole Method (MLFMM)** such that the **computational complexity** becomes $O(N + M)$*



MLFMM applied to Biot-Savart

- ▶ The Multi-Level Fast Multipole Method (MLFMM) is a highly efficient algorithm for evaluating **long-range interactions** in large systems
 - ▶ Electrostatics
 - ▶ Gravitational potential
- ▶ It was originally developed for problems involving $1/|\vec{r} - \vec{r}'|$, Green's functions, such as:

Electrostatics

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} dV'$$

Gravitational potential

$$\phi(\vec{r}) = -G \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} dV'$$

- ▶ For magnetostatics one can use "Biot-Savart" for the vector potential: $\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l}'}{|\vec{r} - \vec{r}'|}$

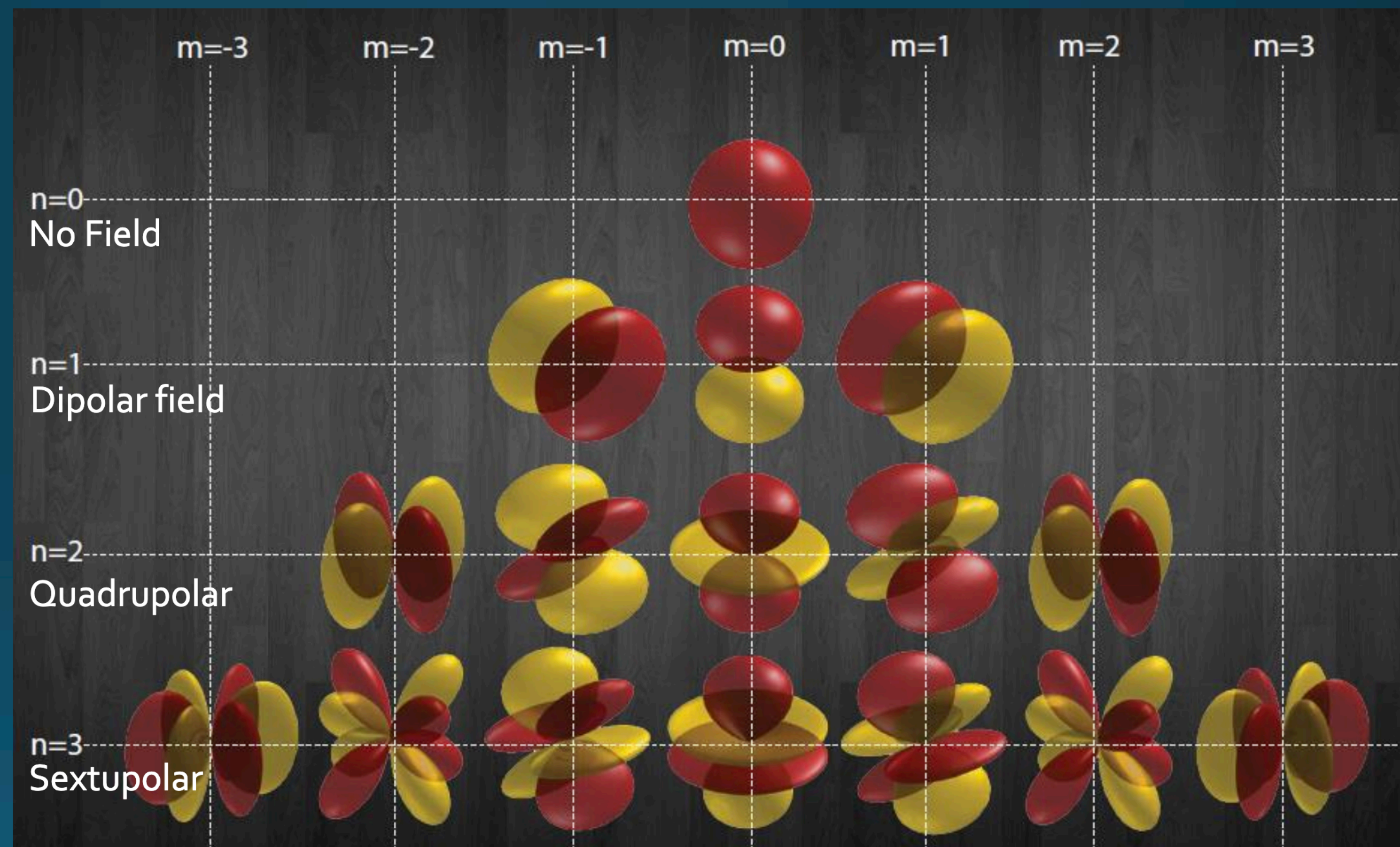


Spherical Harmonics

- Spherical harmonics are all possible solutions of the Laplace equation

$$Y_n^{-m}(\alpha, \beta) = \sqrt{\frac{(n-|m|)!}{(n+|m|)!}} e^{im\beta} P_n^{|m|}(\cos\alpha).$$

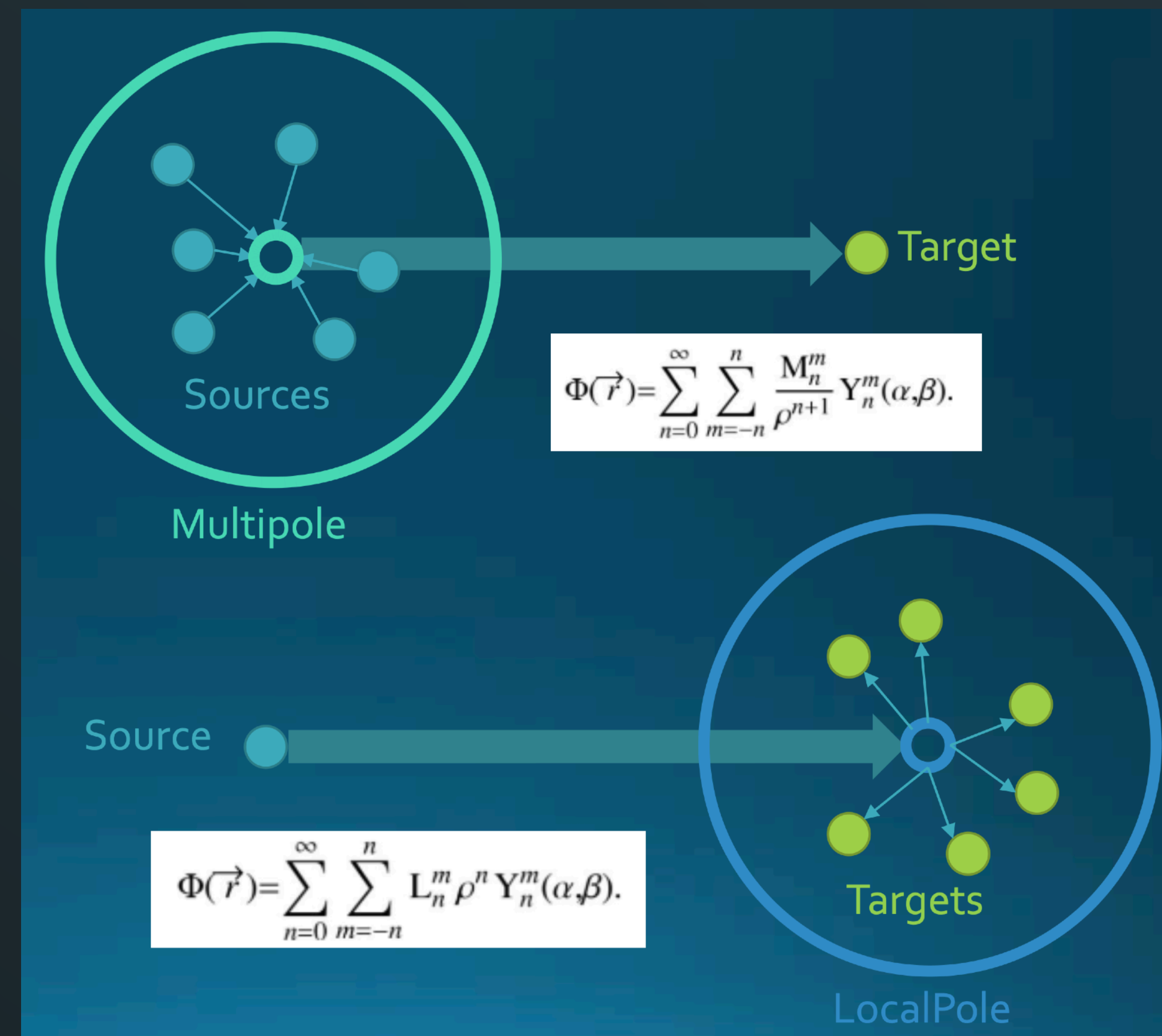
- By using a set of harmonics for each component of the vector potential (A_x, A_y, A_z) it is possible to represent any possible magnetic field
- Where P_n^m are the Legendre polynomials calculated recursively





MLFMM: Multipoles and Localpoles

- ▶ MLFMM use **multipoles** and **localpoles** to represent the field of the sources
- ▶ **Multipoles** represent the field of sources inside a sphere at any target point outside the sphere. It compresses the field to a few components of the Legendre polynomials
- ▶ **Localpoles** represent the field of sources outside a sphere at any target point inside the sphere
- ▶ Multipoles and **localpoles** are therefore essentially opposites
- ▶ Both multipoles and localpoles are described by **spherical harmonics**





Rat for non-linear materials: VIM

Volume Integral Method (VIM):

- ▶ Only magnetic regions are discretized
- ▶ Open-boundary conditions are inherently satisfied
- ▶ No surrounding air mesh required

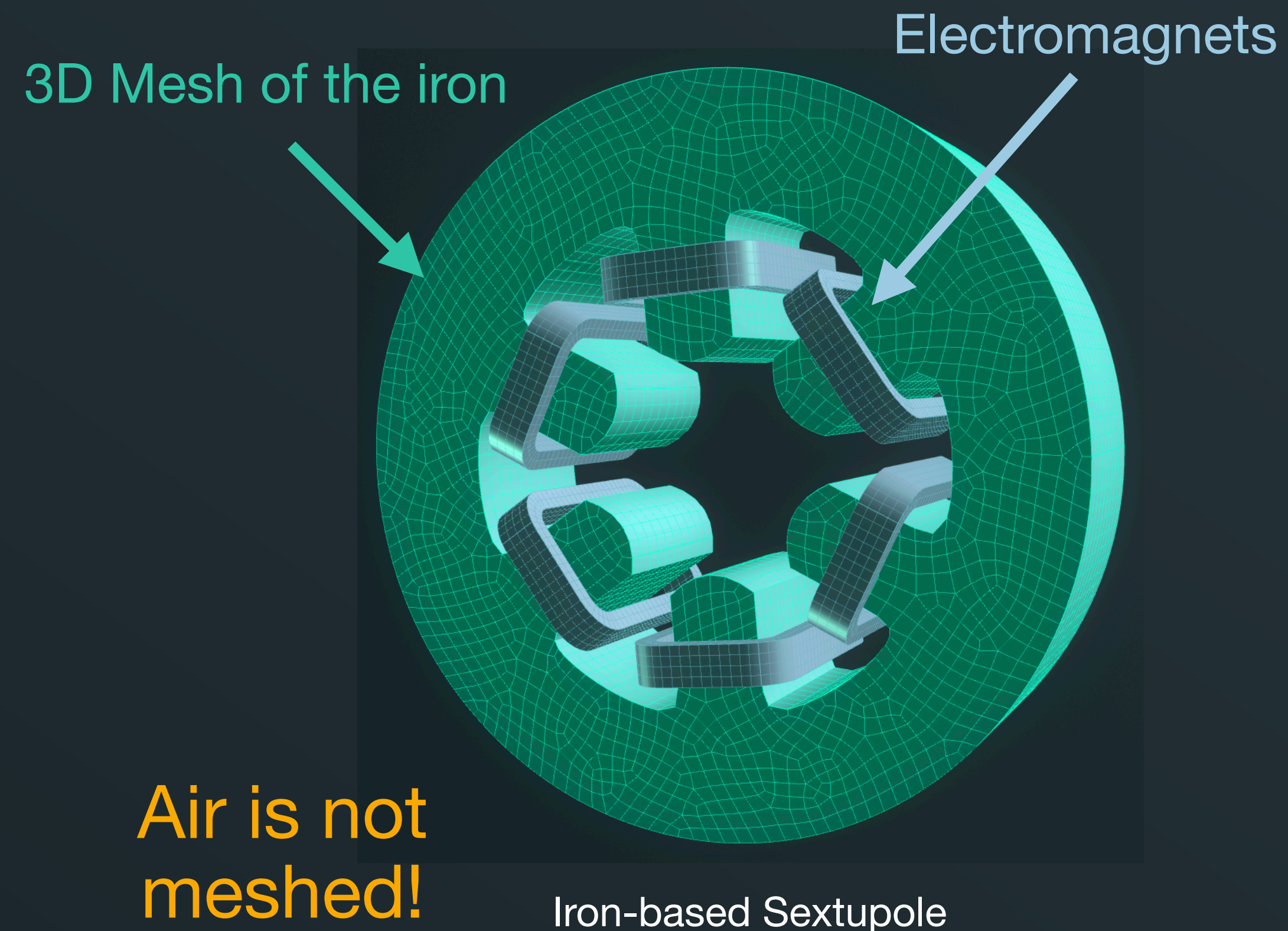
Nonlinear magnetization

The magnetic flux density depends on the local magnetic field:

- ▶ $\mathbf{B} = \mu_0 \mu_r(\mathbf{H})\mathbf{H}$

Resulting problem:

- ▶ Dense long-range interaction system
- ▶ Nonlinear material response
- ▶ Solved iteratively

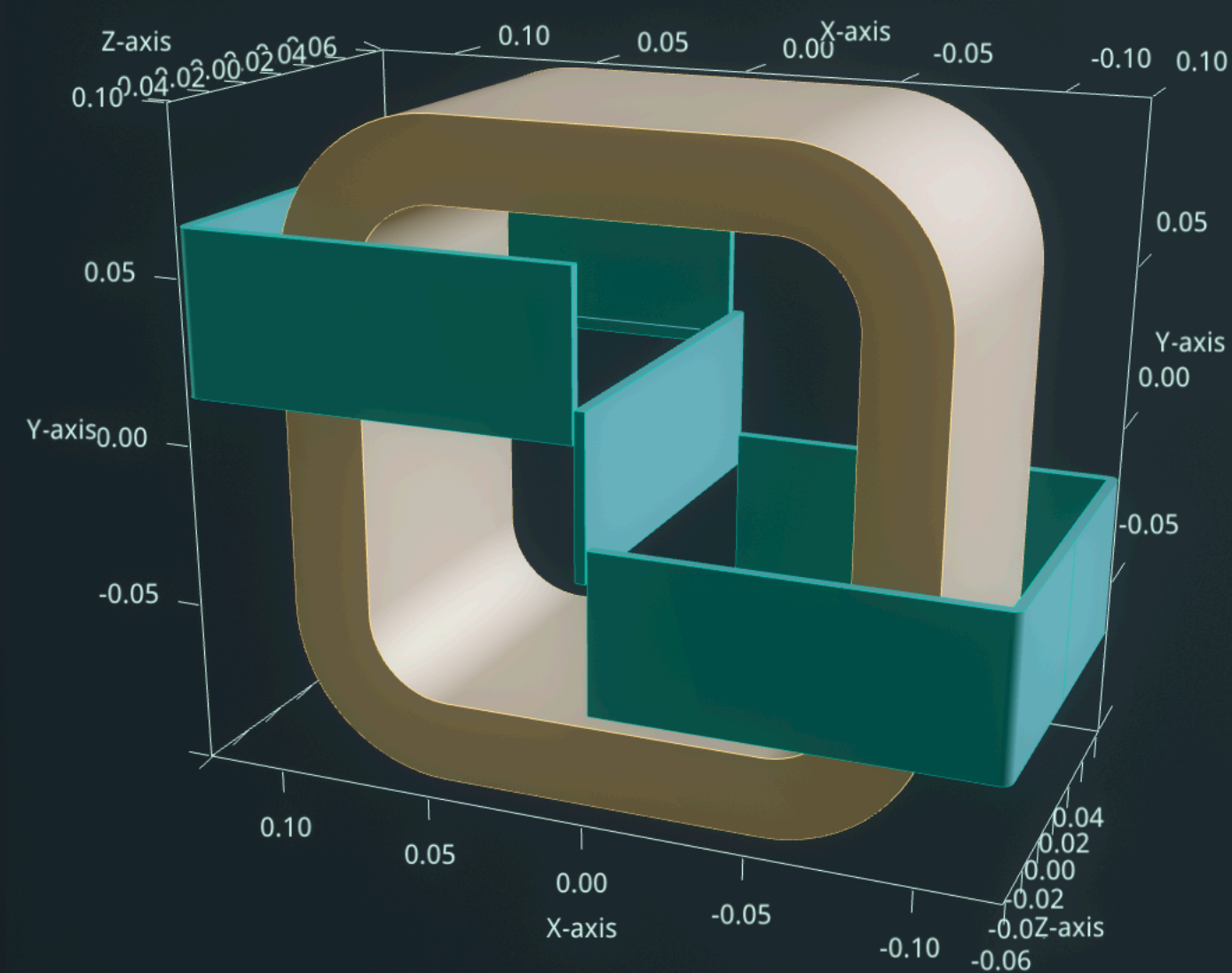




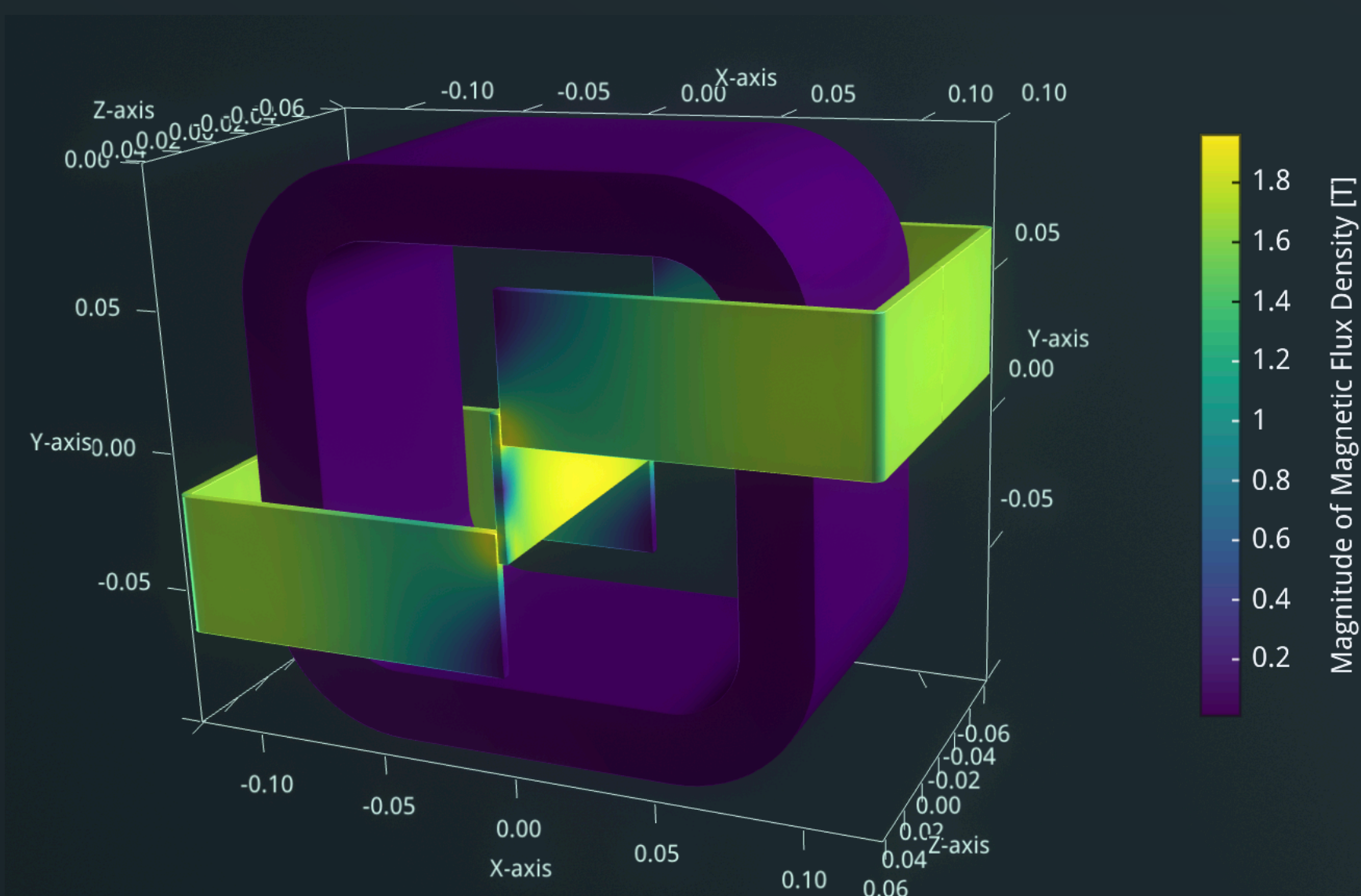
Validating VIM with magnetic measurements

Using the TEAMs (Testing Electromagnetic Analysis Methods) problems

- ▶ Validate Rat against magnetic measurements
- ▶ TEAM 13 problem: Calculate magnetic field at different points for two steel channel excited by a coil
- ▶ HB-curve provided in the problem statement, as well as measure data
<https://www.compumag.org/wp/wp-content/uploads/2018/06/problem13.pdf>
- ▶ V. Le-Van, G. Meunier, O. Chadebec, and J.-M. Guichon, "A Magnetic Vector Potential Volume Integral Formulation for Nonlinear Magnetostatic Problems," *IEEE Transactions on Magnetics*, vol. 52, no. 3, pp. 1–4, Mar. 2016, doi: 10.1109/TMAG.2015.2490627.



→
Calculation





Validating Rat with magnetic measurements

Using the TEAMs (Testing Electromagnetic Analysis Methods) problems

- ▶ V. Le-Van, G. Meunier, O. Chadebec, and J.-M. Guichon, “A Magnetic Vector Potential Volume Integral Formulation for Nonlinear Magnetostatic Problems,” *IEEE Transactions on Magnetics*, vol. 52, no. 3, pp. 1–4, Mar. 2016, doi: 10.1109/TMAG.2015.2490627.
- ▶ Comparing @ 3000AT and plotting the field along a line in x, we find a match with measured data within 2%

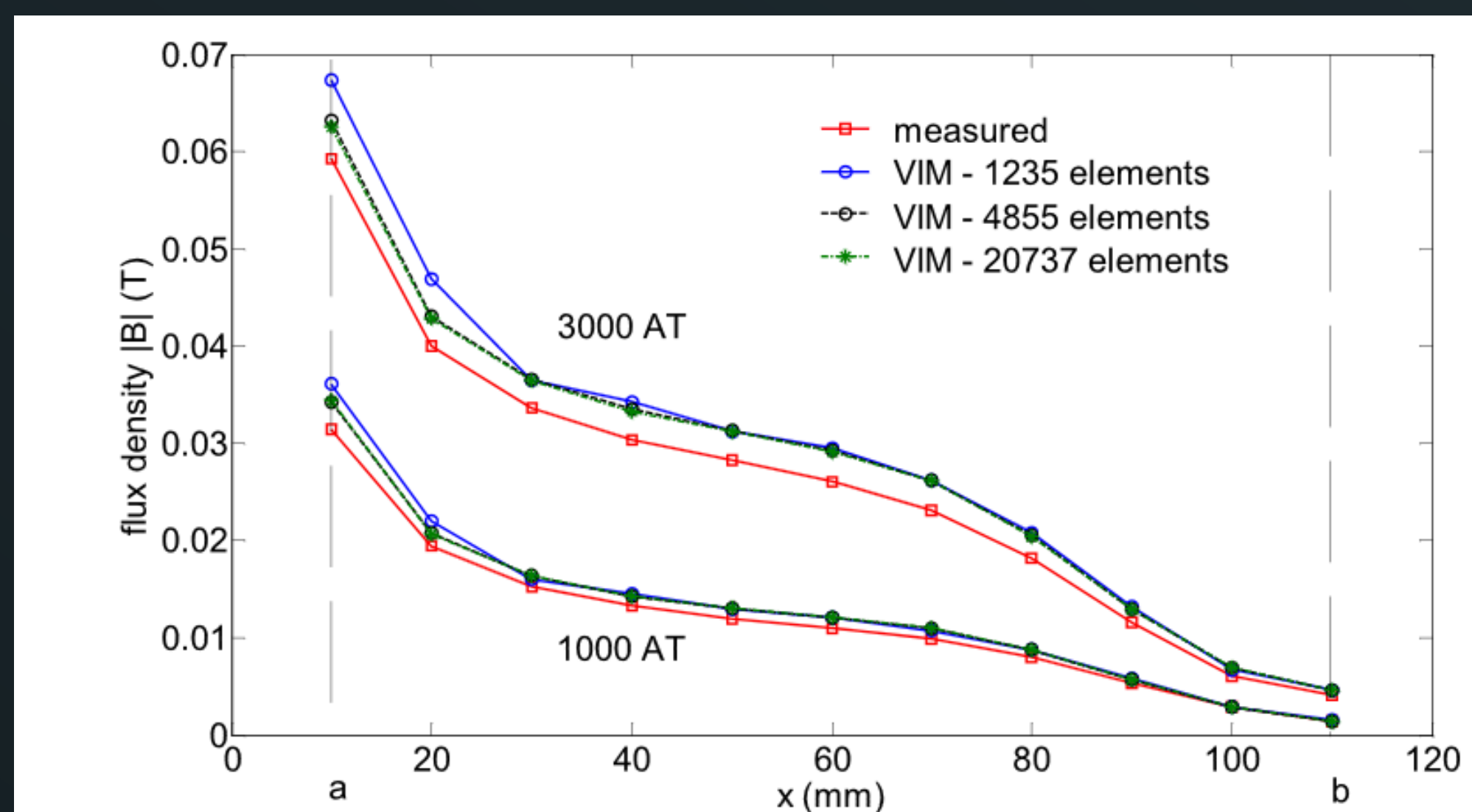
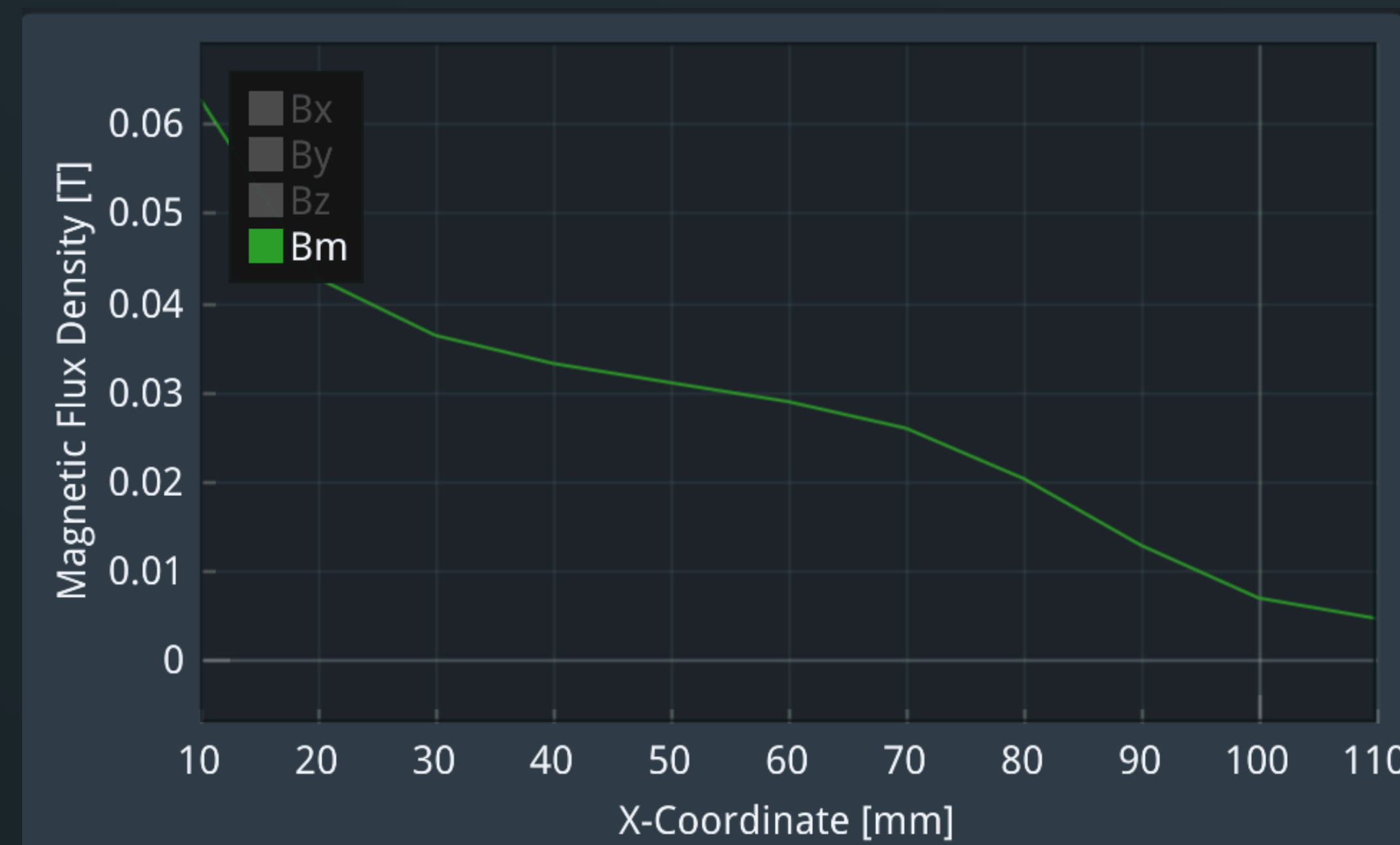
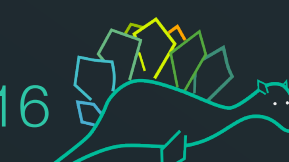


Fig. 7. Spatial distribution of magnetic flux density in air.





More than just the mathematical method





The building blocks of Rat

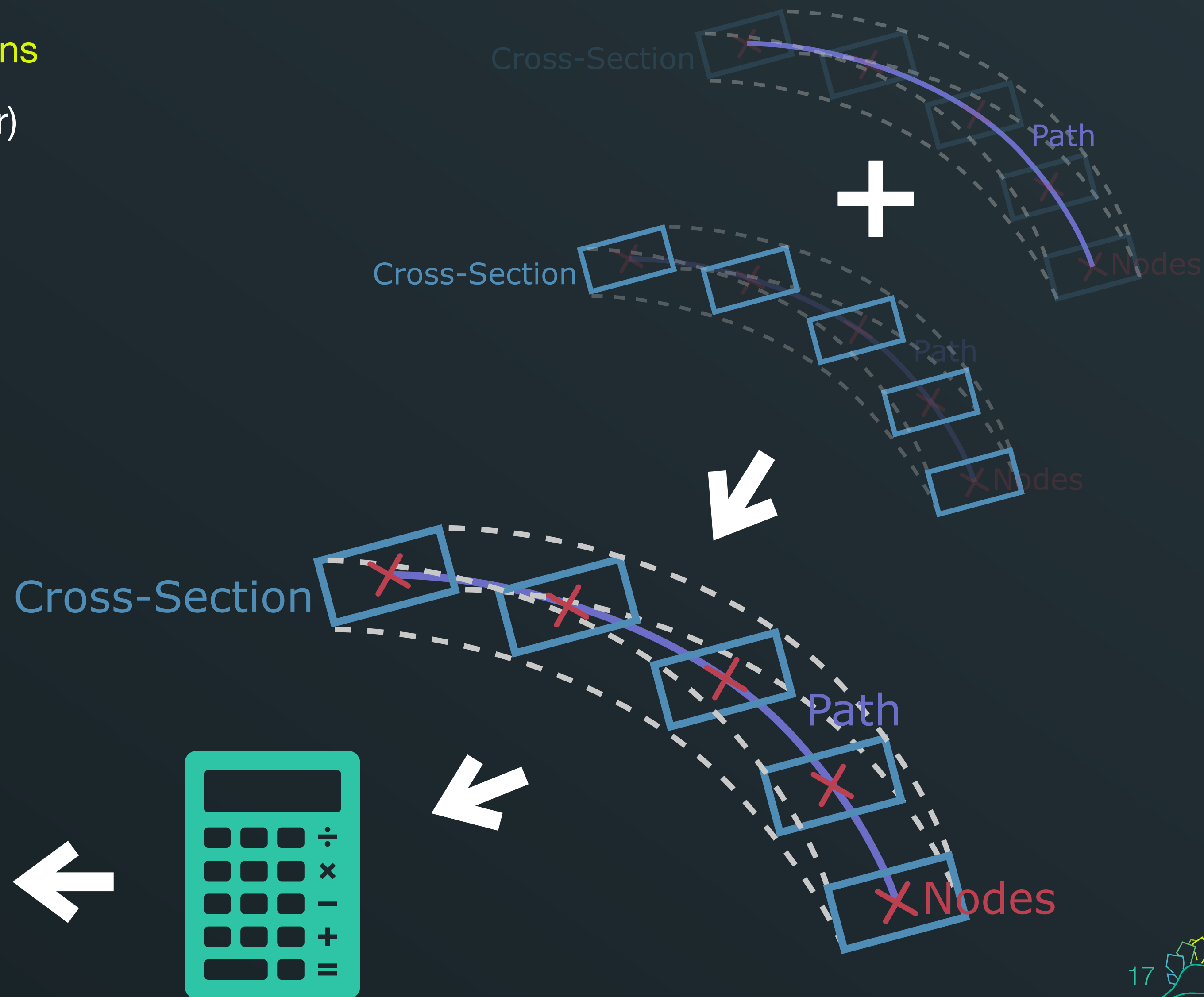
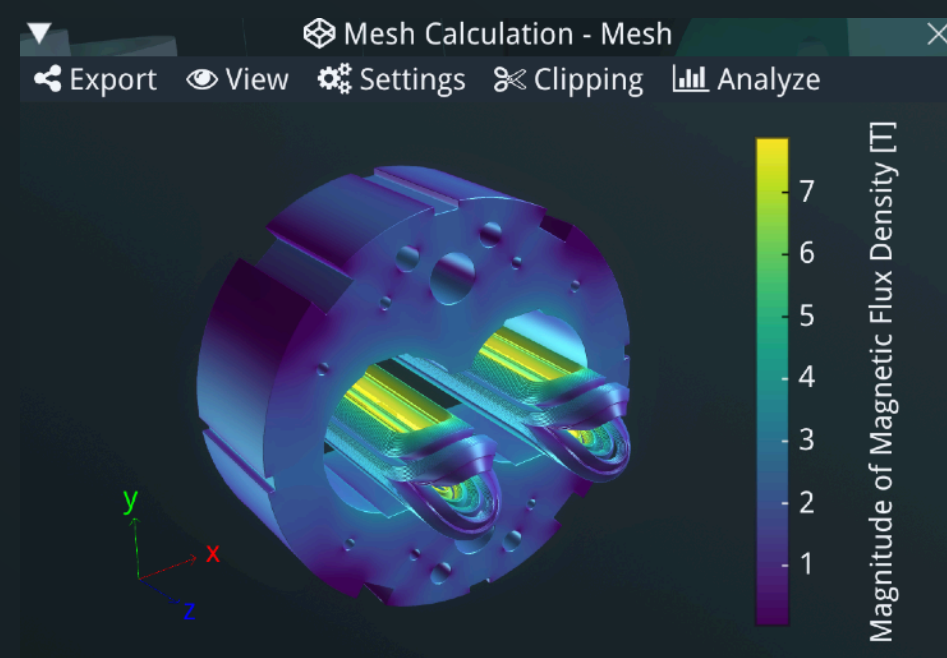
▶ First you **model the coil/magnet in three dimensions**

1. Take a **path** (windings of you conductor)
2. Extrude a **cross-section**

▶ This **model is fed to the calculator** to obtain:

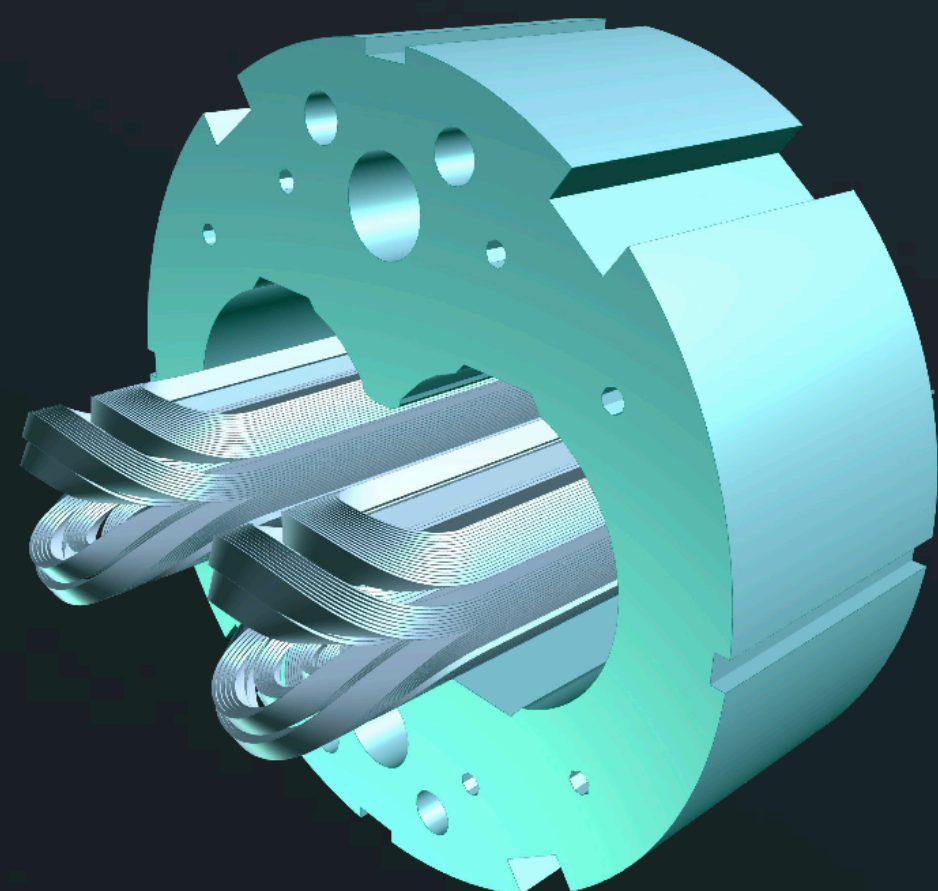
- ▶ Field maps in 1D, 2D and 3D
- ▶ Harmonics
- ▶ Quench for superconductors
- ▶ Particle tracking

▶ **Results can be analysed** in Rat or exported





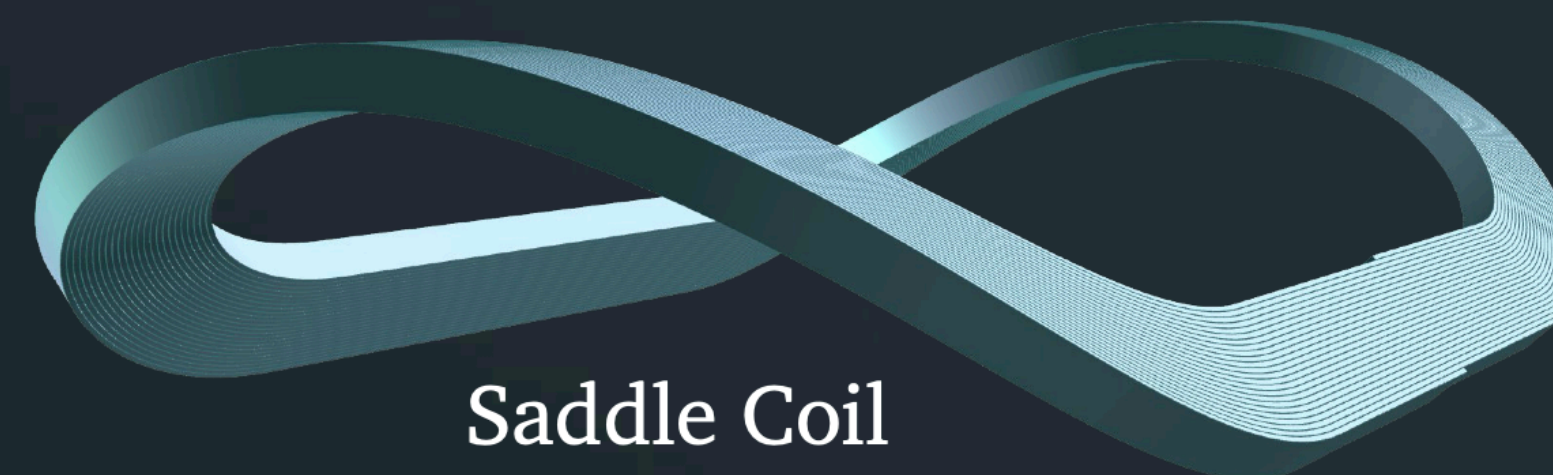
Many build in shapes



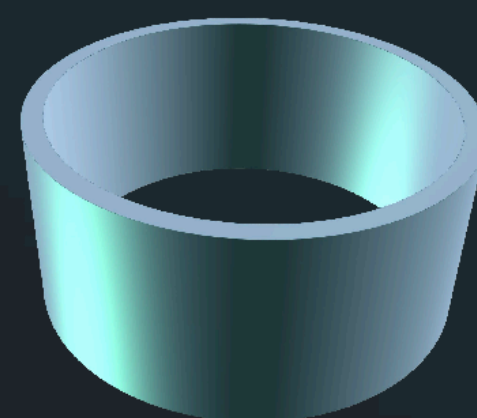
Cos-Theta



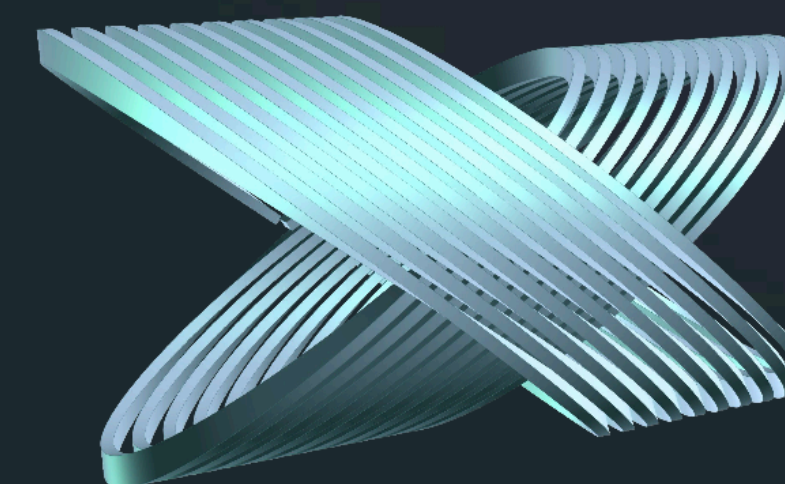
Flared Coil



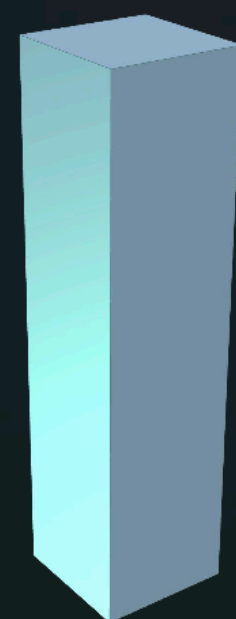
Saddle Coil



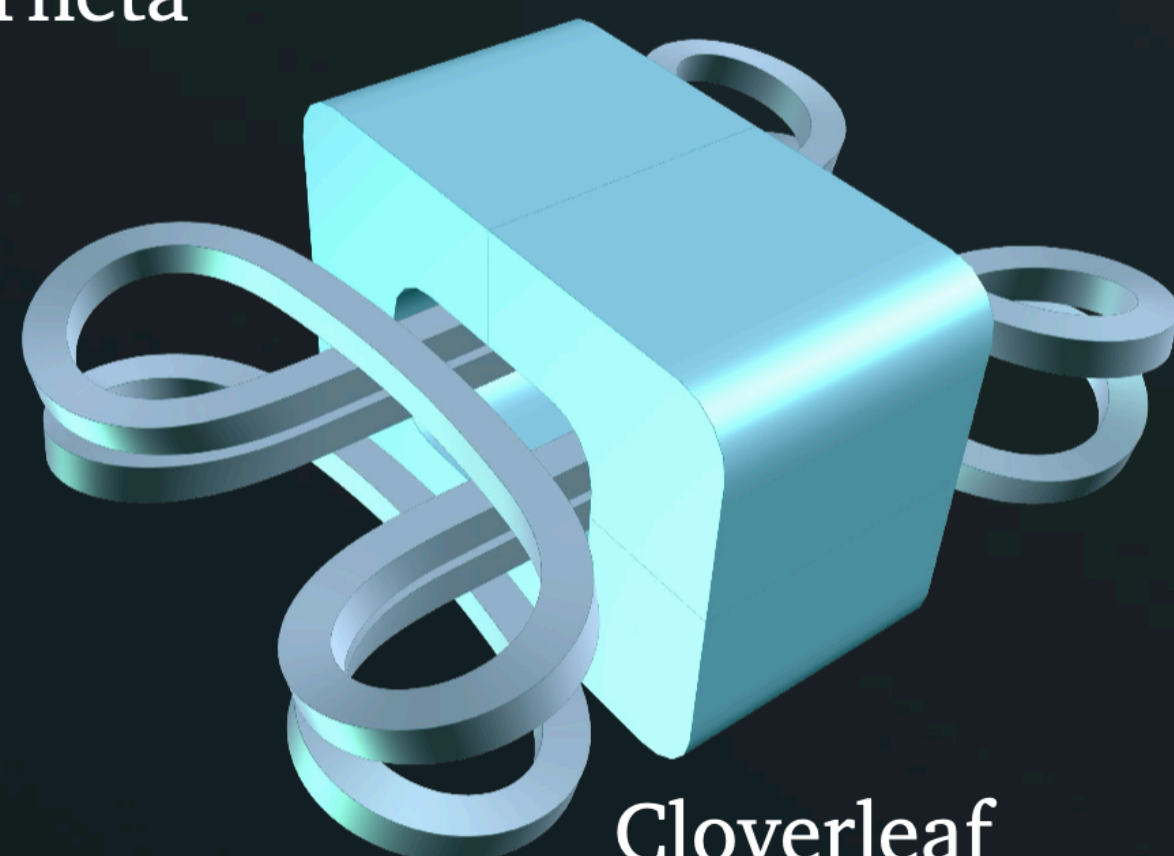
Solenoid



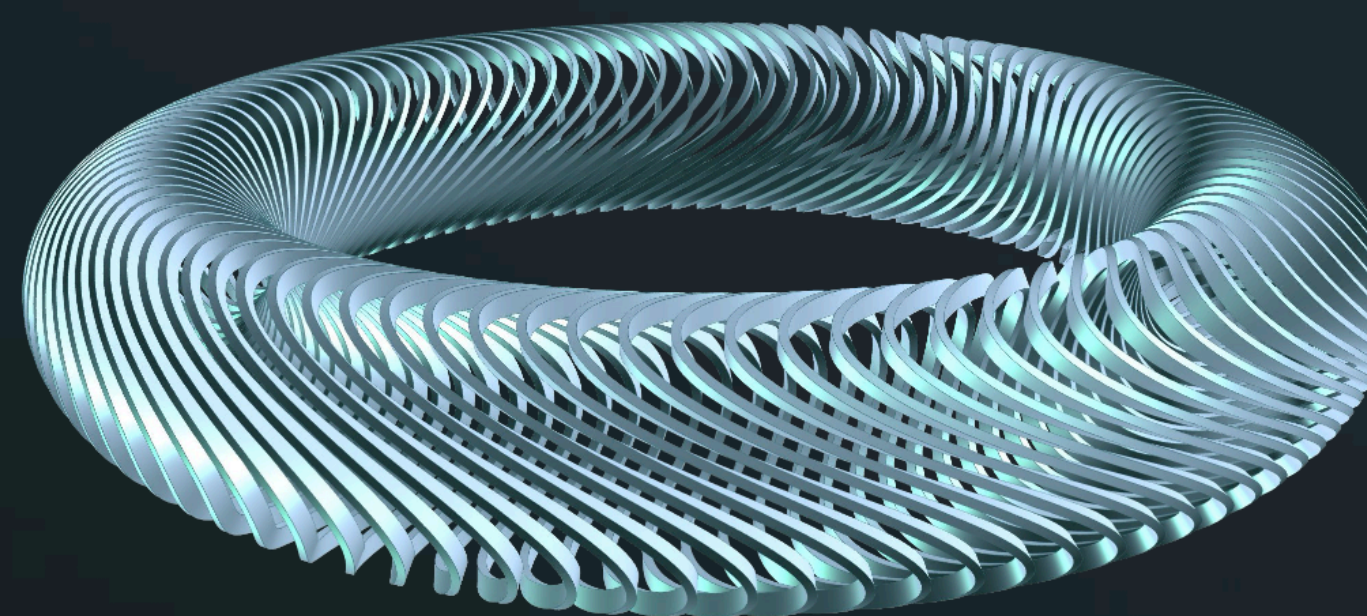
Regular CCT



Bar Magnet



Cloverleaf

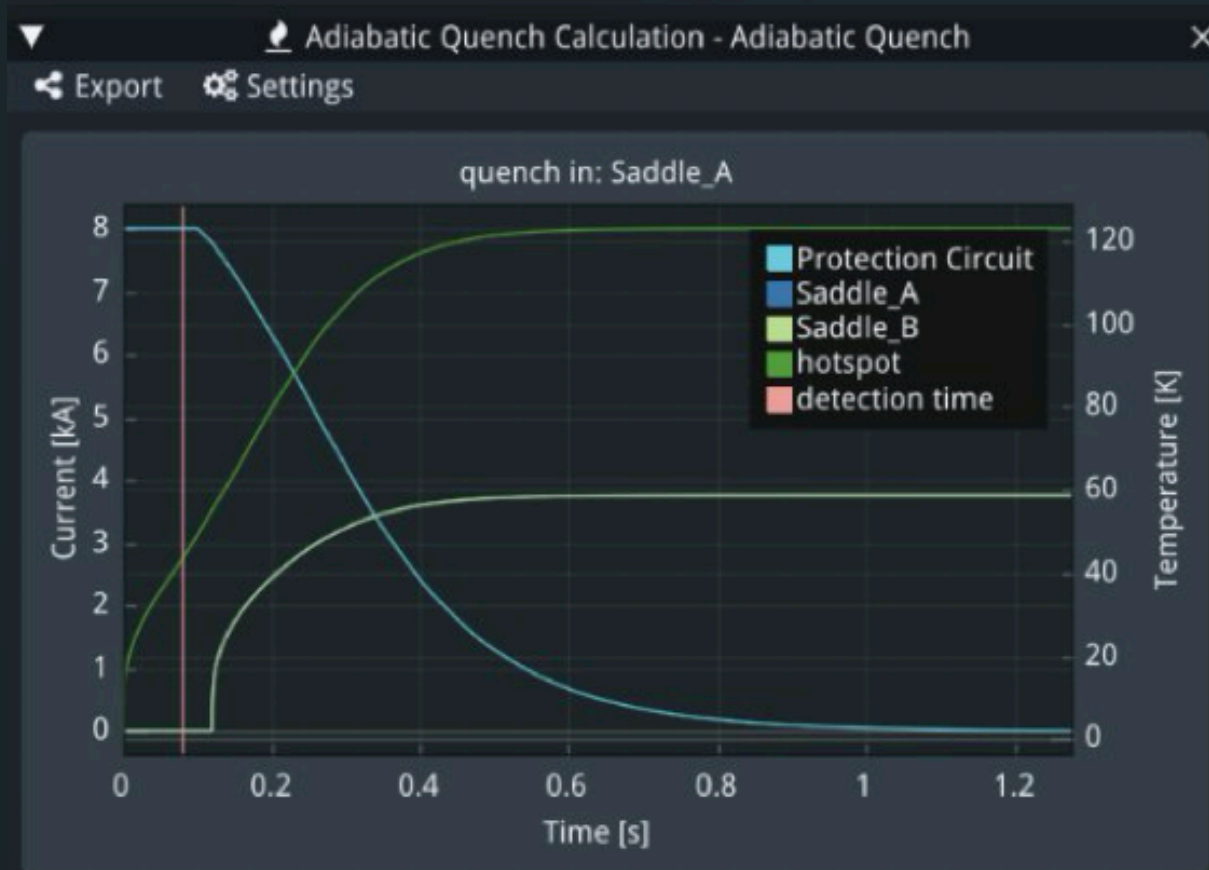


Custom CCT

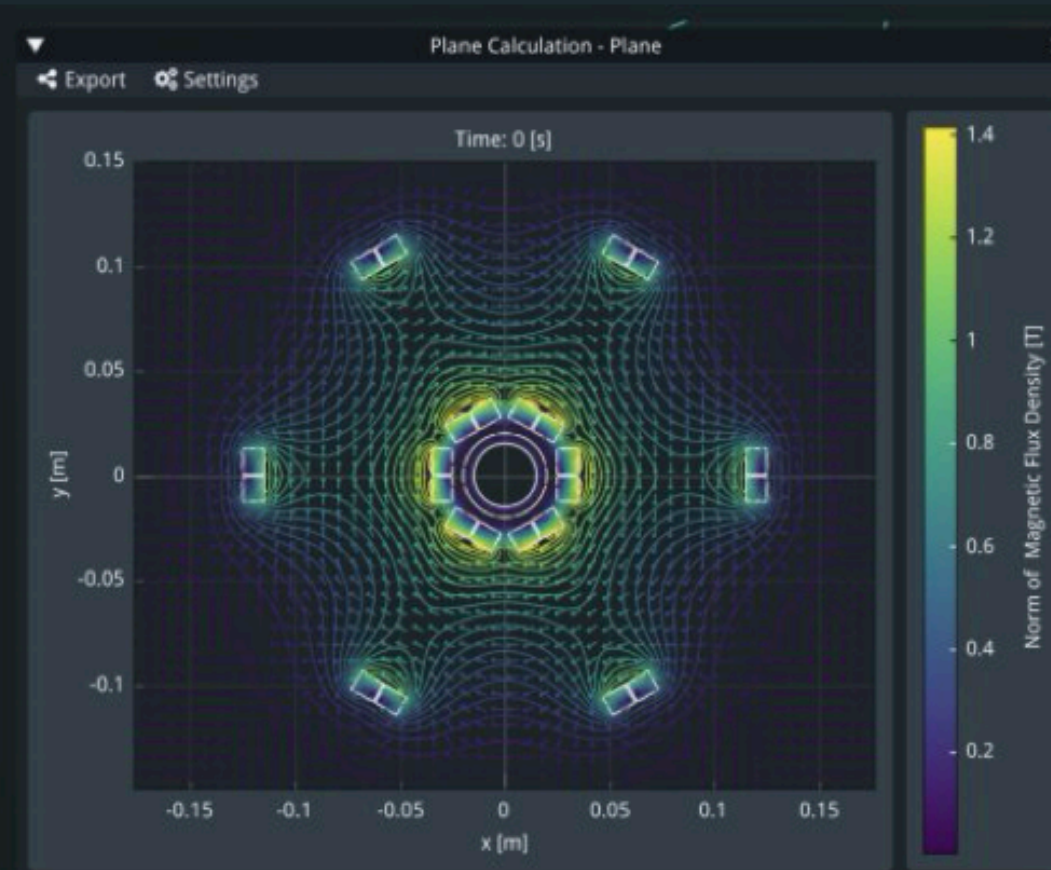
And More ...



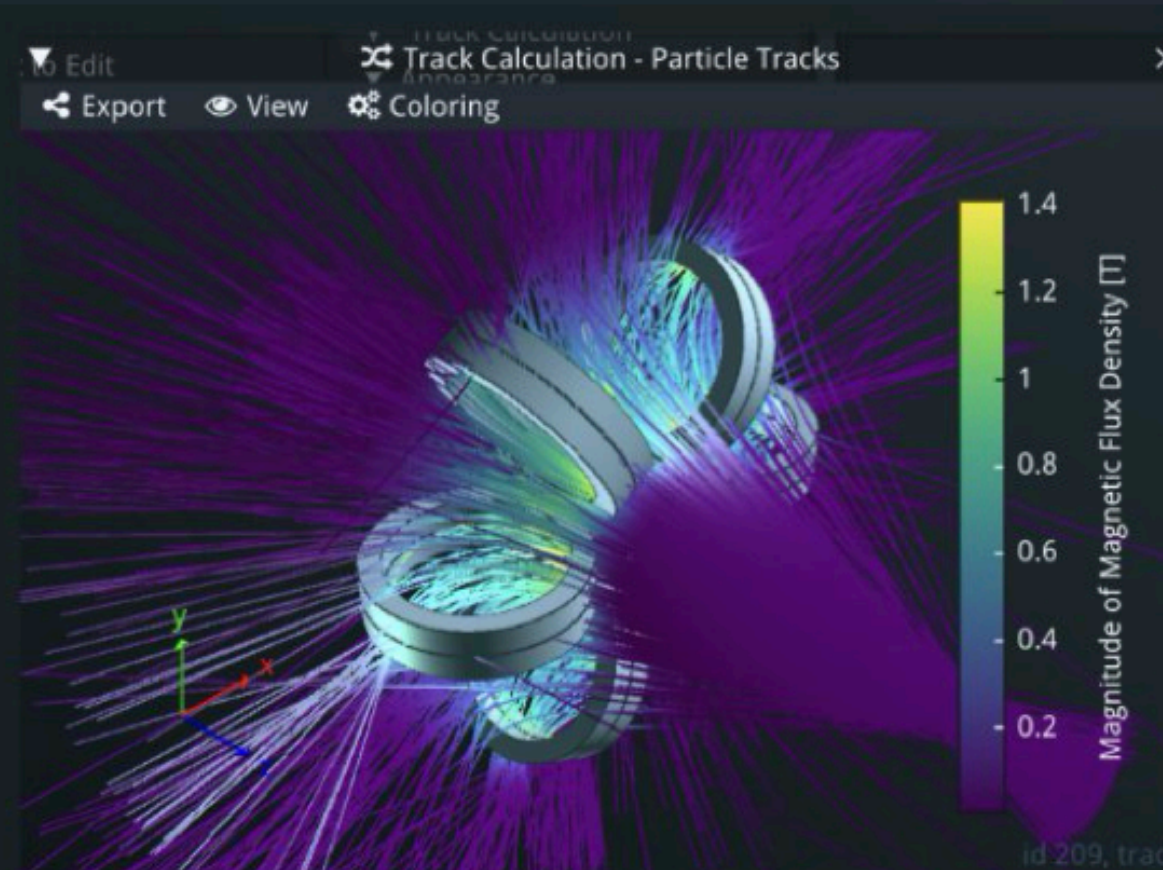
Many build in calculations



Adiabatic Quench (new)

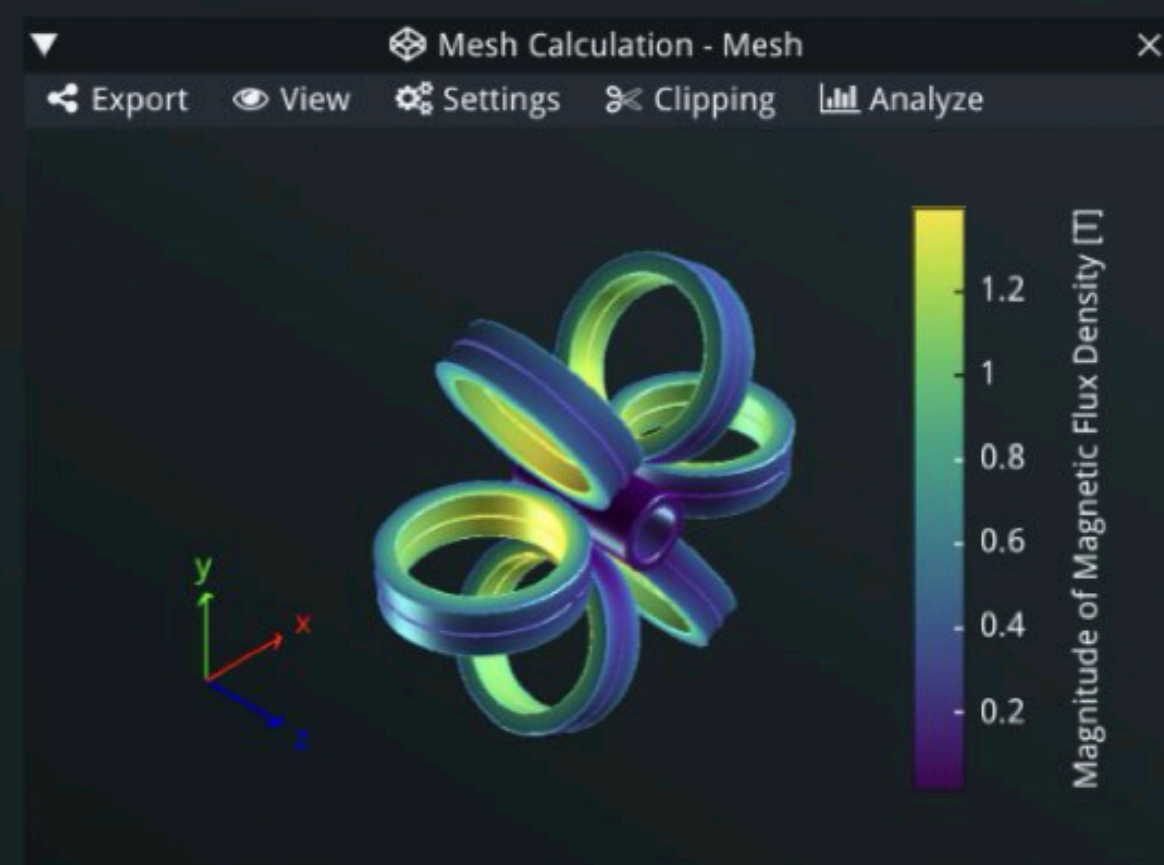


Plane Calculation

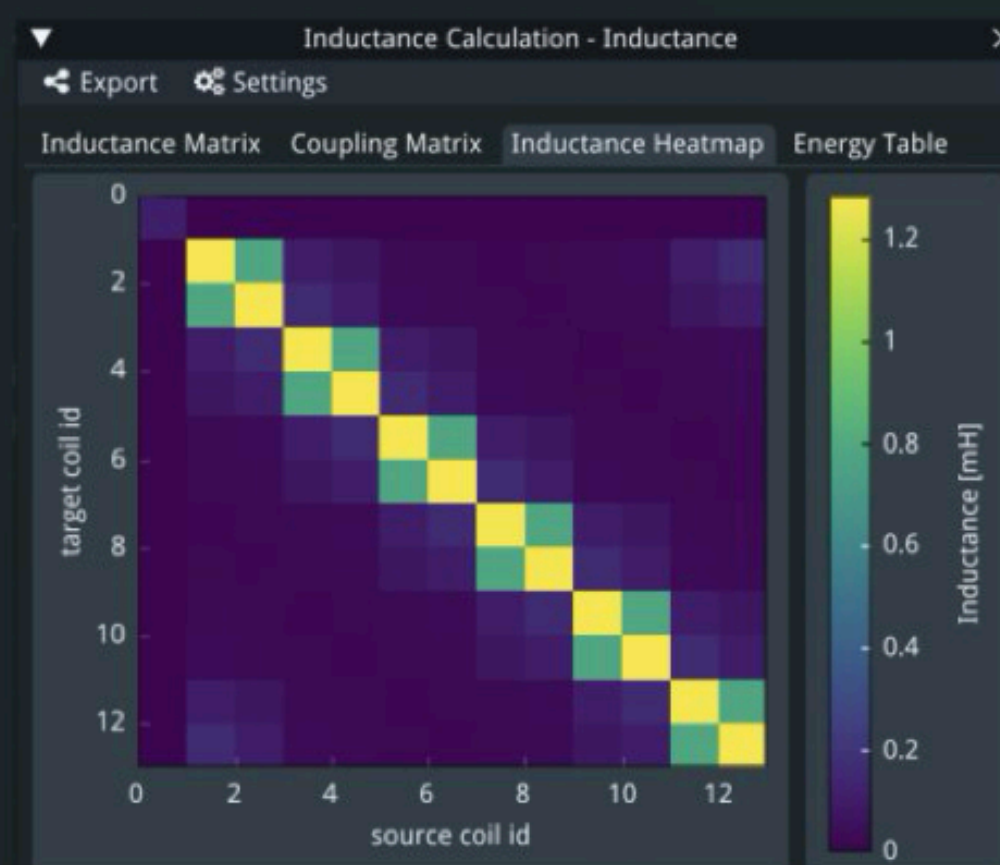


Particle Tracks

- ▶ 1, 2, 3D field
- ▶ Inductance
- ▶ Particle tracking
- ▶ Quench
- ▶ Thermal margin, current density, relative permeability, force density on a mesh
- ▶ Harmonics



Mesh Calculation



Inductance Calculation

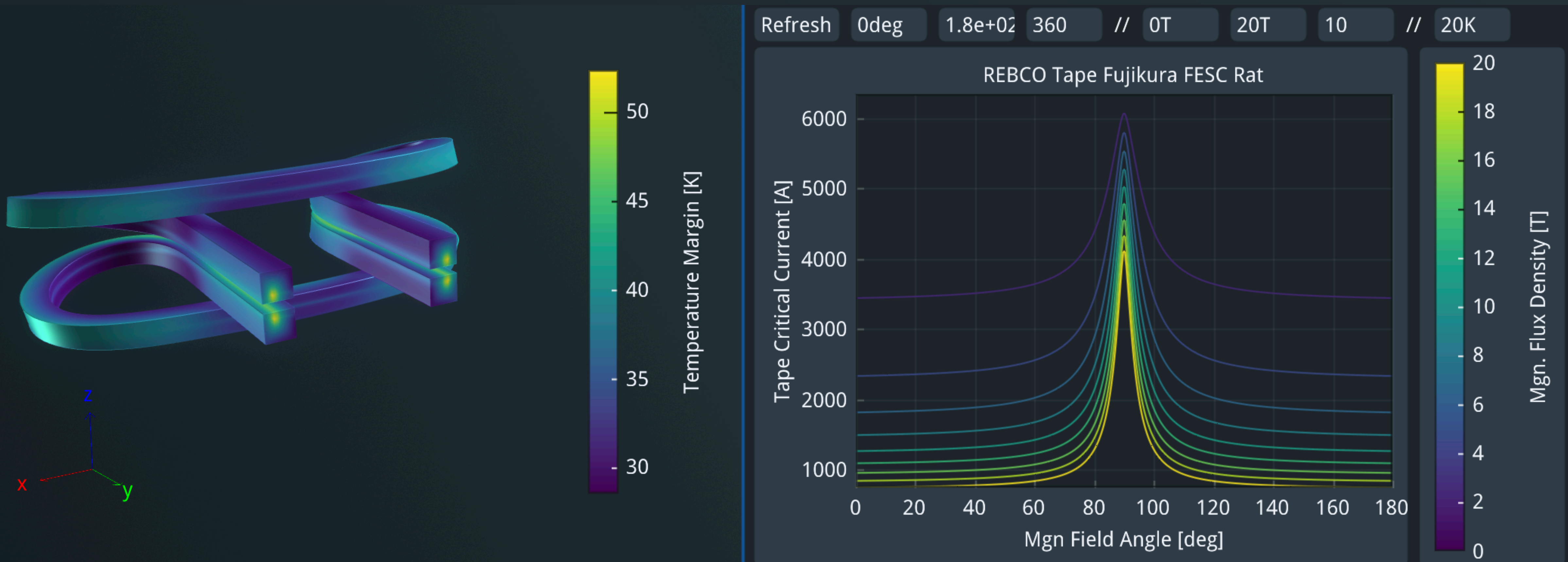


Line Calculation



Many HTS Related Features

- ▶ For example angular dependent critical current fit allows plotting the temperature margin on the surface of the coil.





Rat for IDs:

Extending VIM for Permanent Magnets





Extending VIM for Permanent Magnets

- ▶ ESRF pointed out that the VIM method could be extended to permanent magnets, and it turns out it can:
 - ▶ **Added remanent flux density** -> right hand side offset to the system of equations.
 - ▶ Susceptibility calculation includes offset flux.
 - ▶ Anisotropic Material model for Susceptibility in addition to the isotropic model.

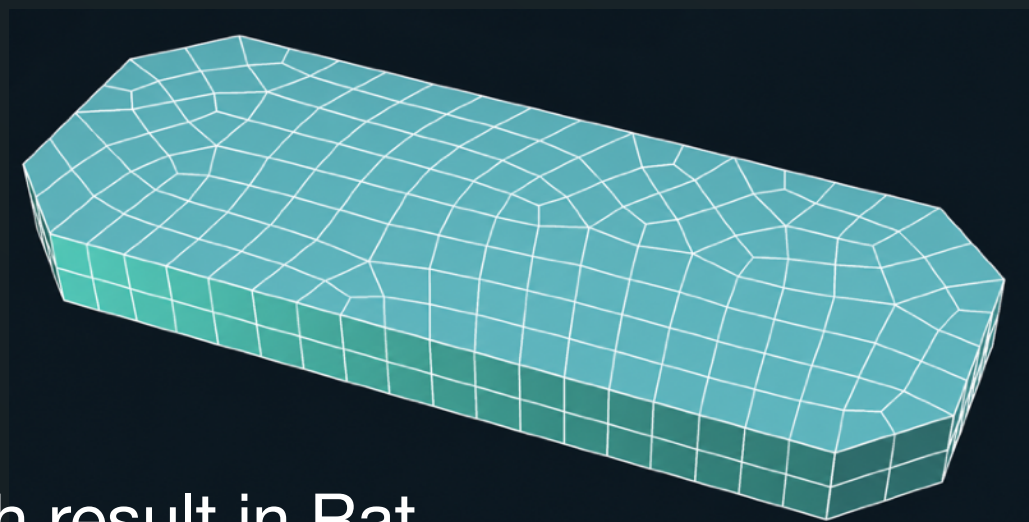
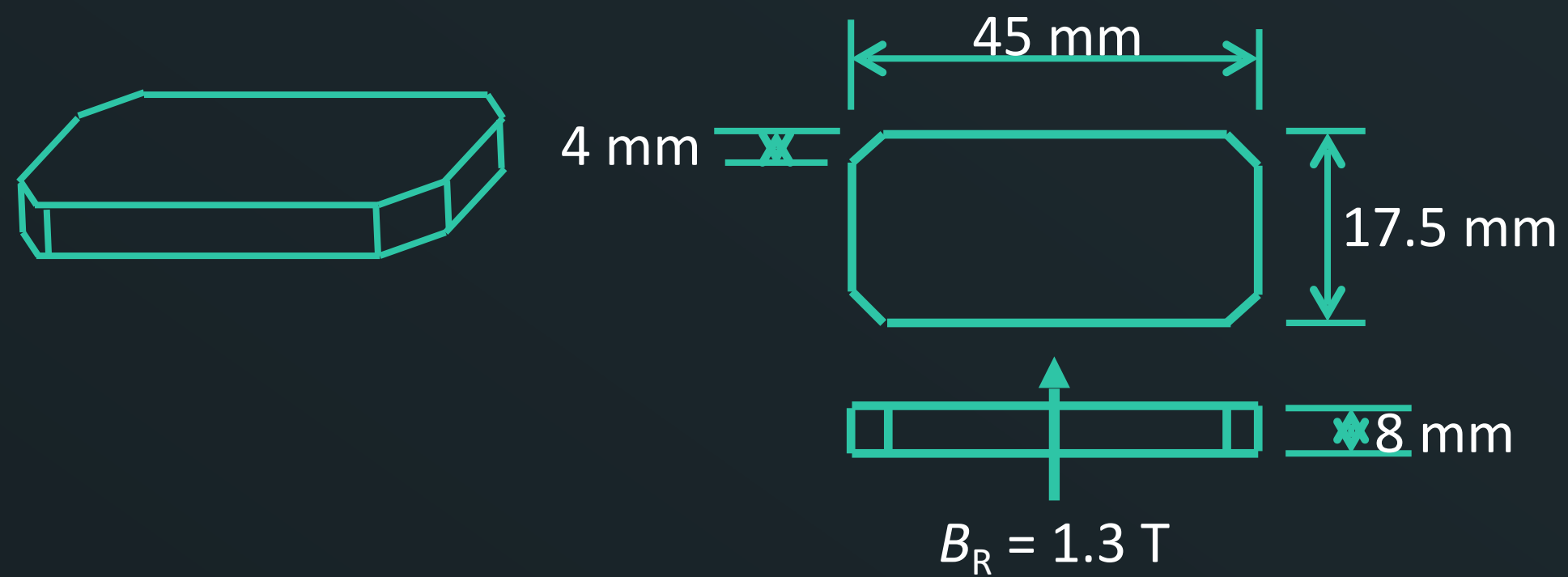
$$\mathbf{M} = \mathbf{M}_R + \chi \mathbf{H} \quad \chi = \begin{pmatrix} \chi_{\parallel} & 0 & 0 \\ 0 & \chi_{\perp} & 0 \\ 0 & 0 & \chi_{\perp} \end{pmatrix}$$



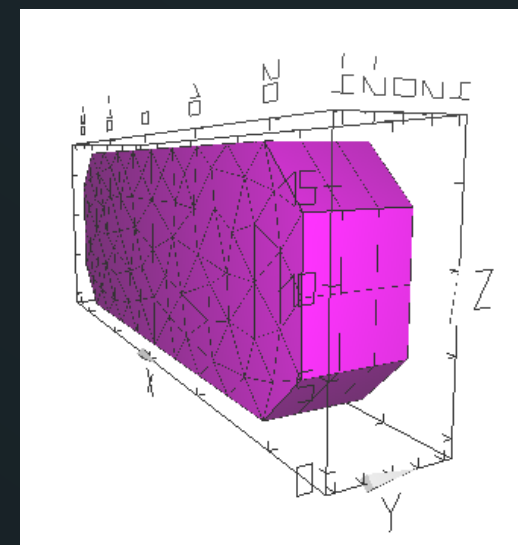
Validating Rat with a simple Undulator magnet

Start from a single undulator magnet

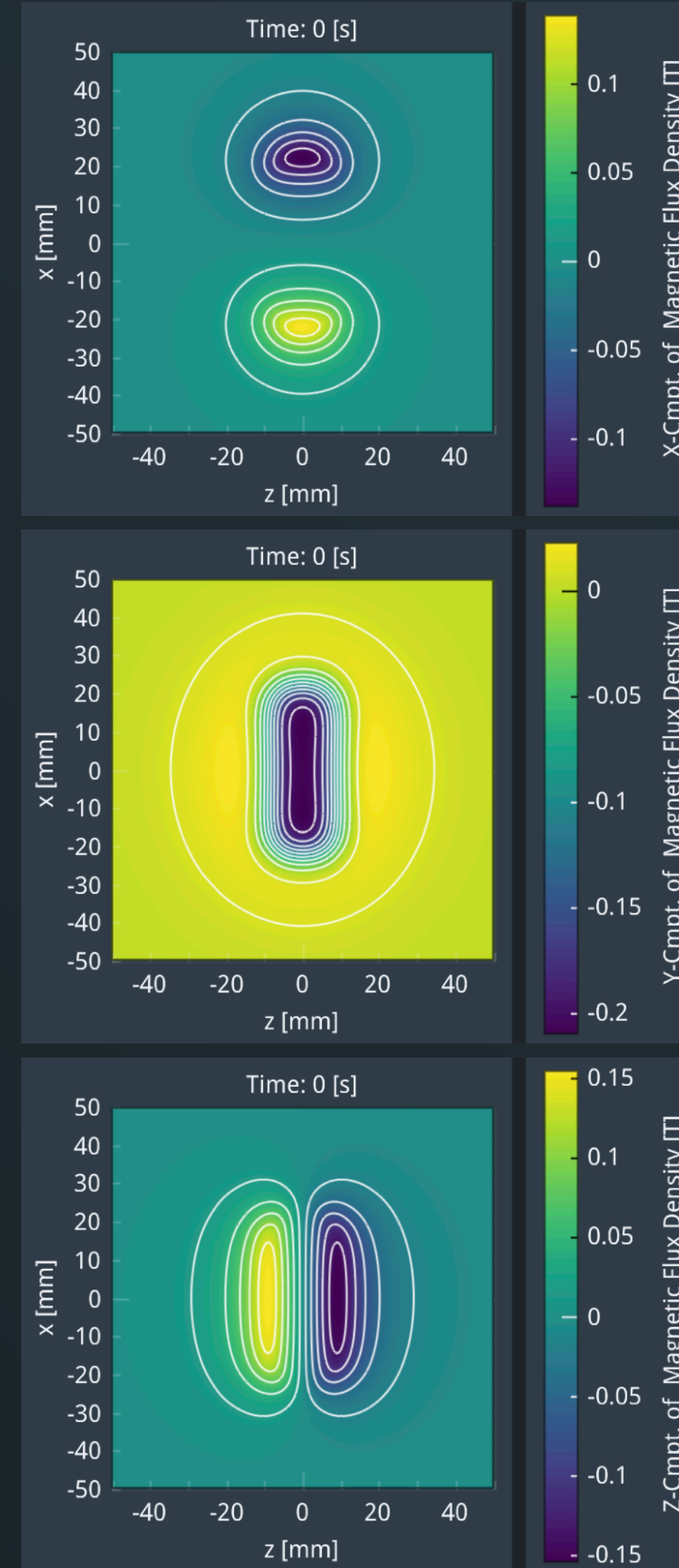
- ▶ Reproduce the 3D shape in Rat, using Distmesh
- ▶ Set the 1.3T B_R
- ▶ Assume anisotropic, constant magnetisation
- ▶ Compare results to Radia simulation of the magnetic field



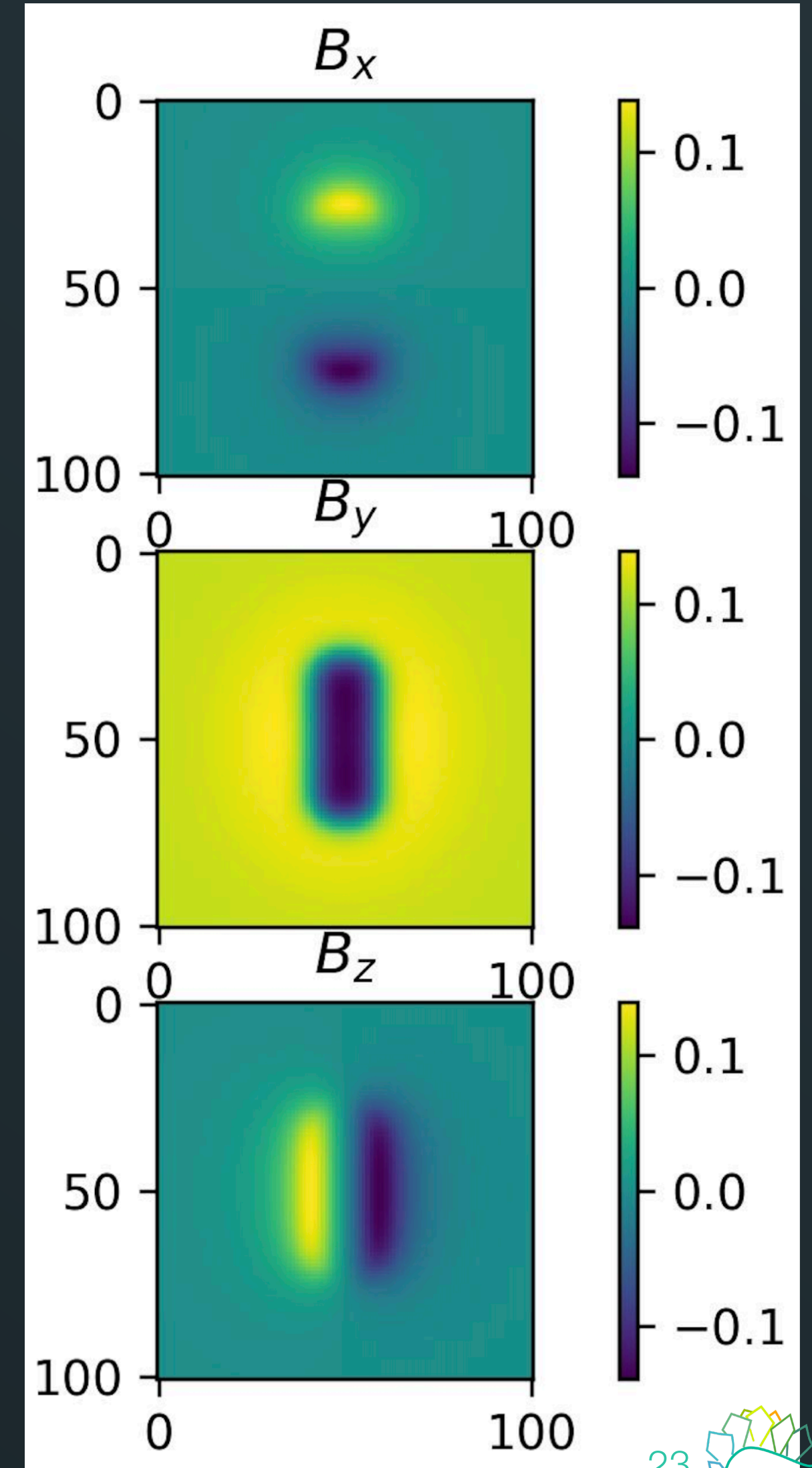
Distmesh result in Rat



Difference between Radia and Rat: 2mT



Rat



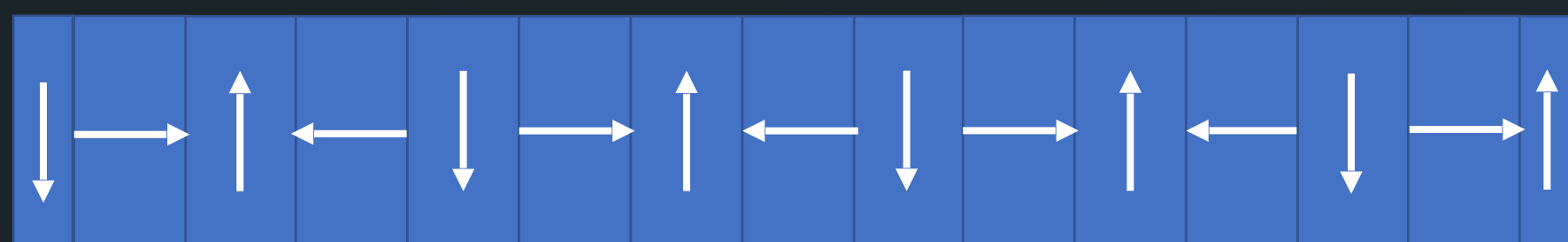
Radia



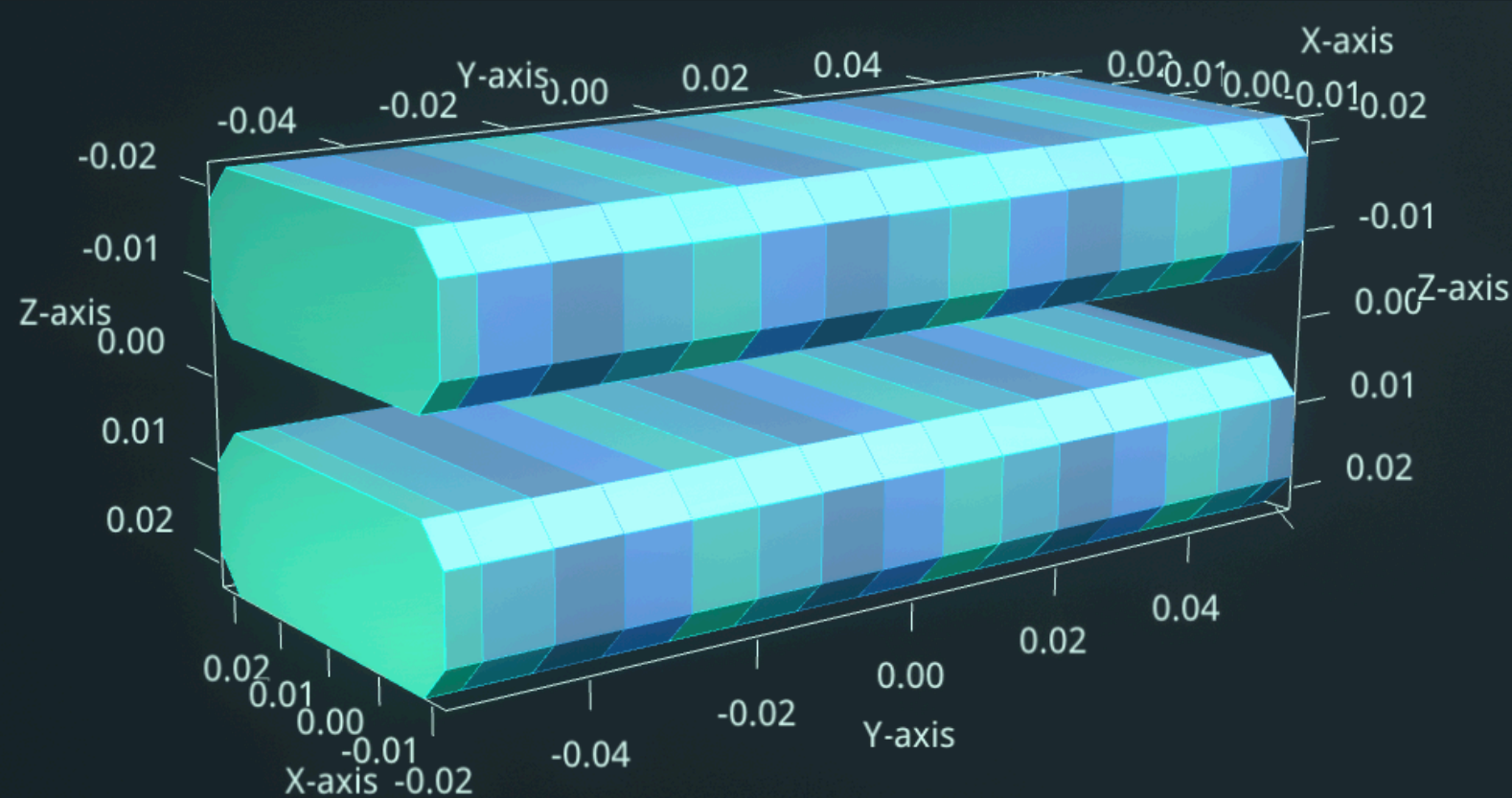
Validating Rat with a simple Undulator model

Repeat this for a simple undulator

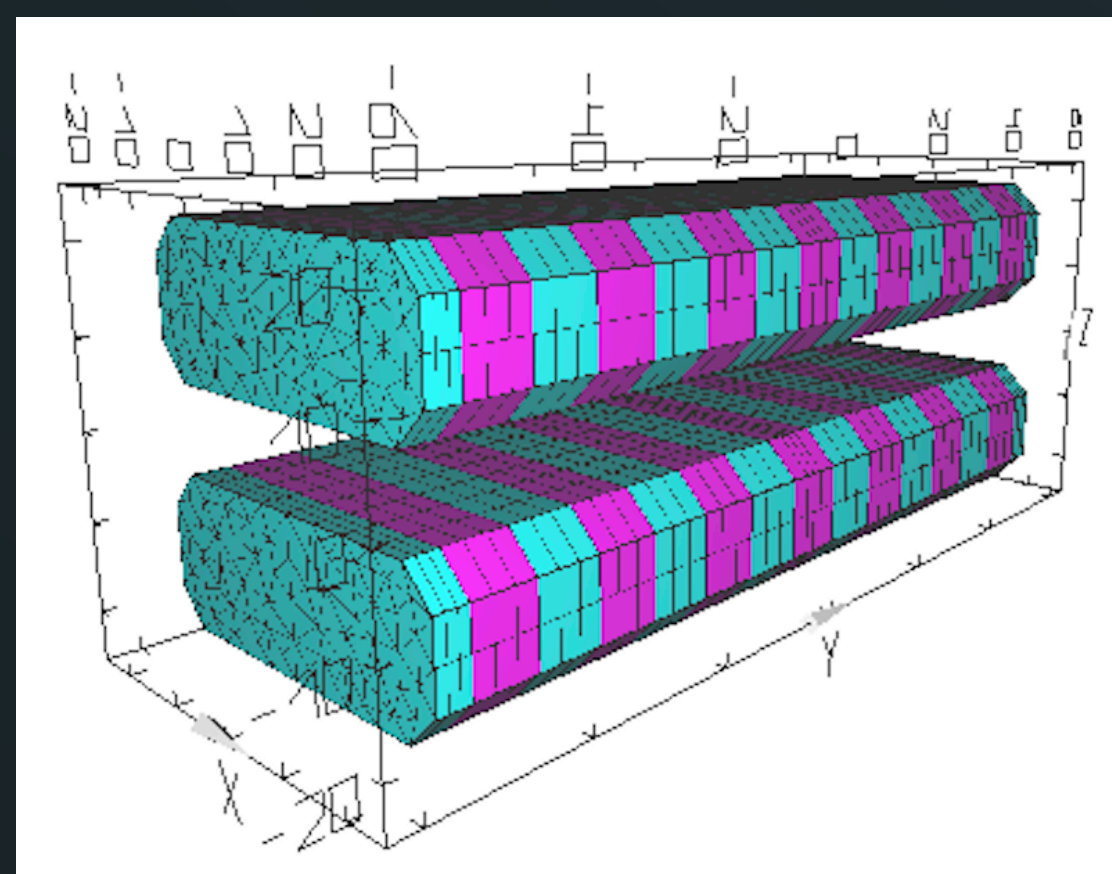
- ▶ Reproduce the 3D shape in Rat, using Distmesh
- ▶ Set the magnetisation separately for each magnet
- ▶ Compare results to Radia simulation of the magnetic field



Magnetisation direction for the magnets

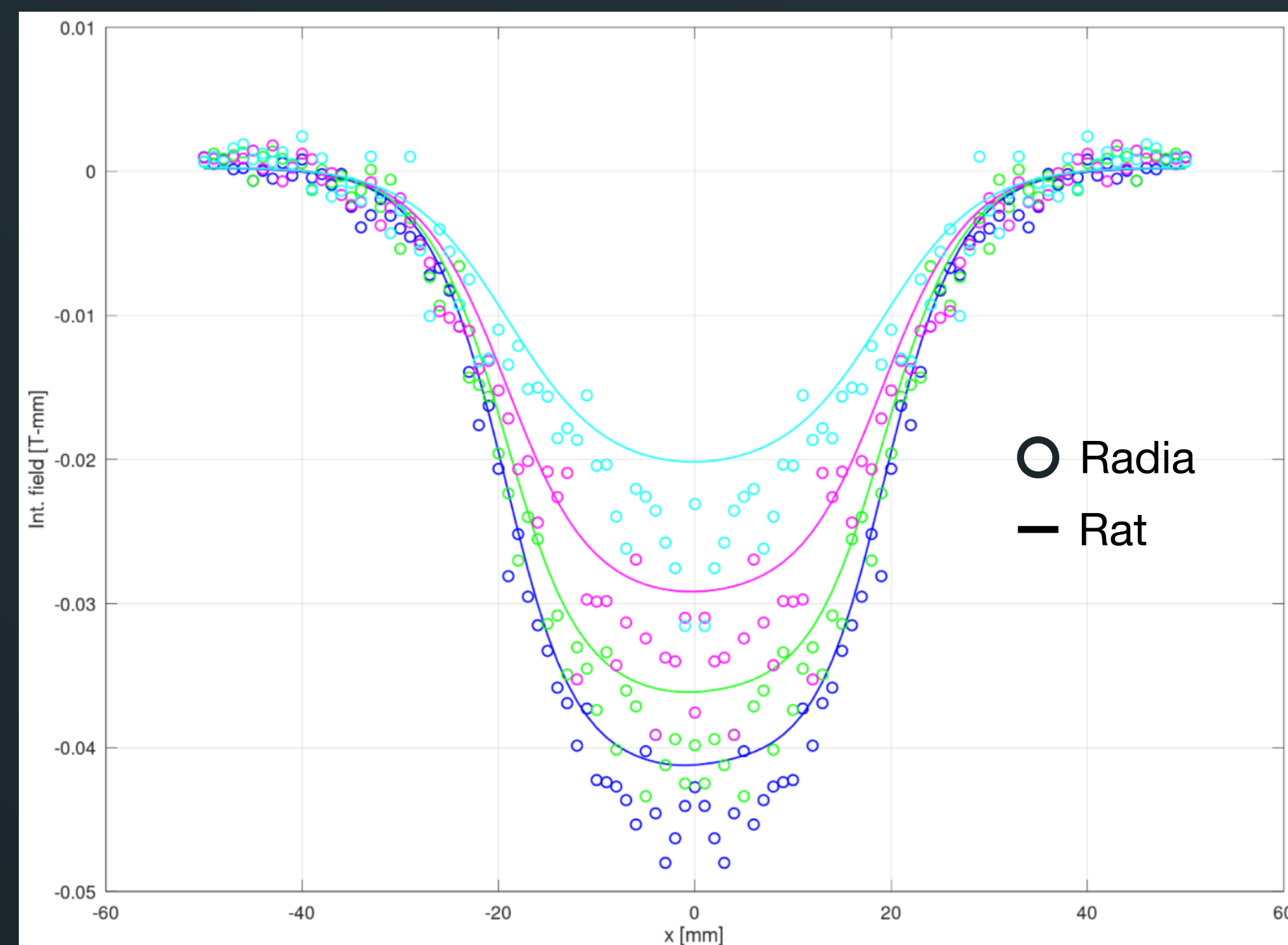


Simple undulator in Rat



Simple undulator in Radia

Integrated B-field along different x-lines



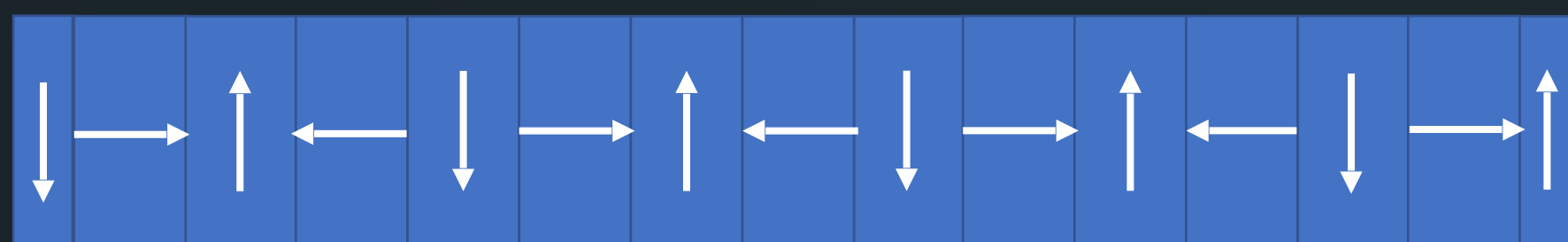
Difference between Radia and Rat in the order of mT



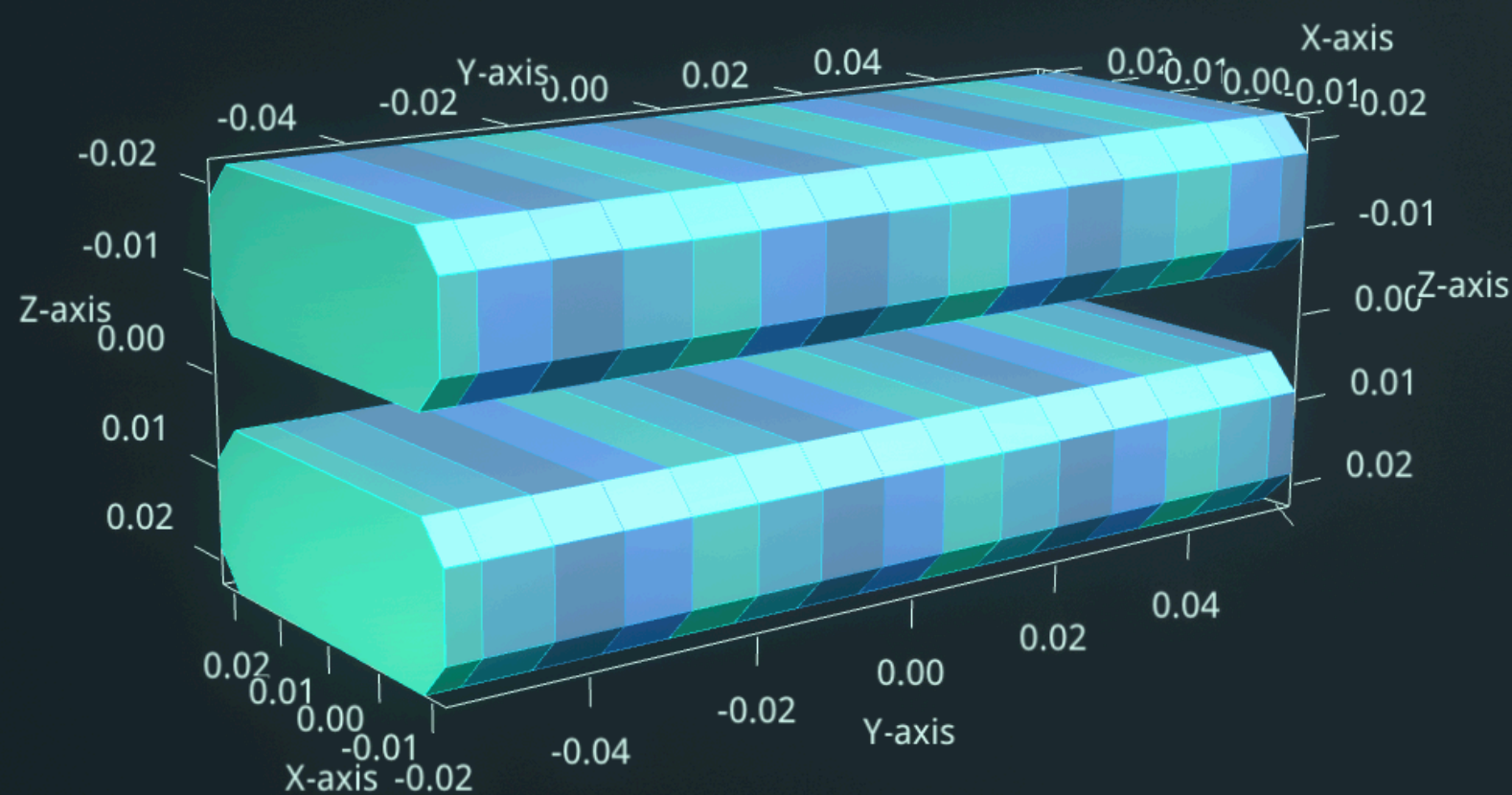
Validating Rat with a simple Undulator model

Repeat this for a simple undulator

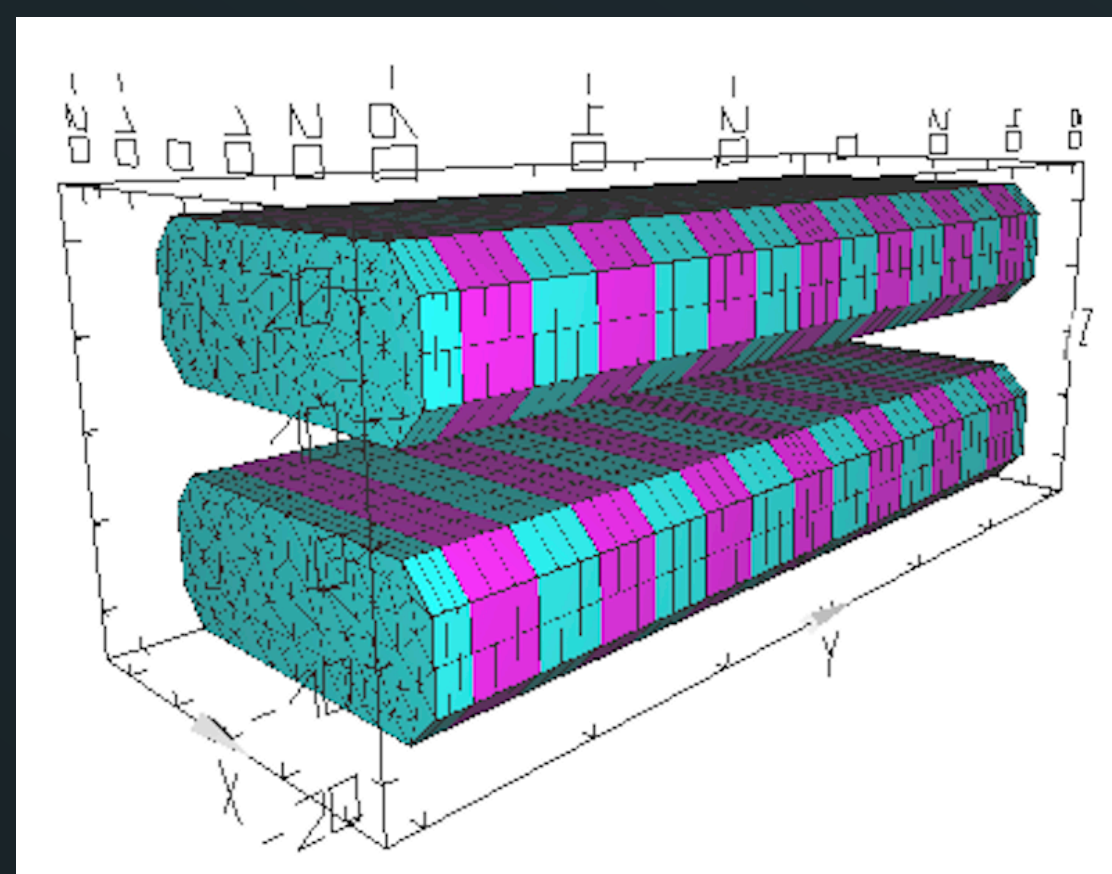
- ▶ Reproduce the 3D shape in Rat, using Distmesh
- ▶ Set the magnetisation separately for each magnet
- ▶ Compare results to Radia simulation of the magnetic field



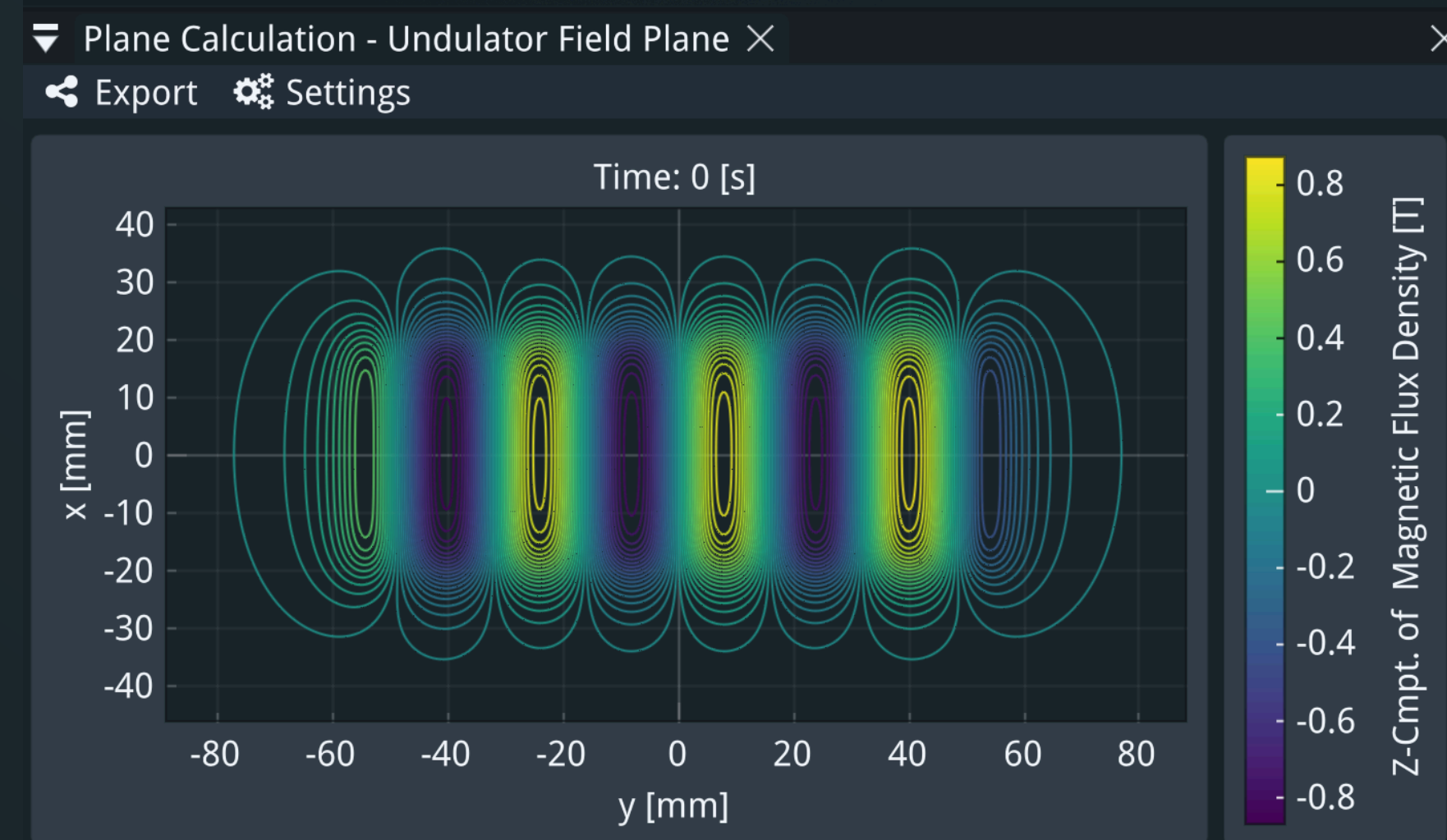
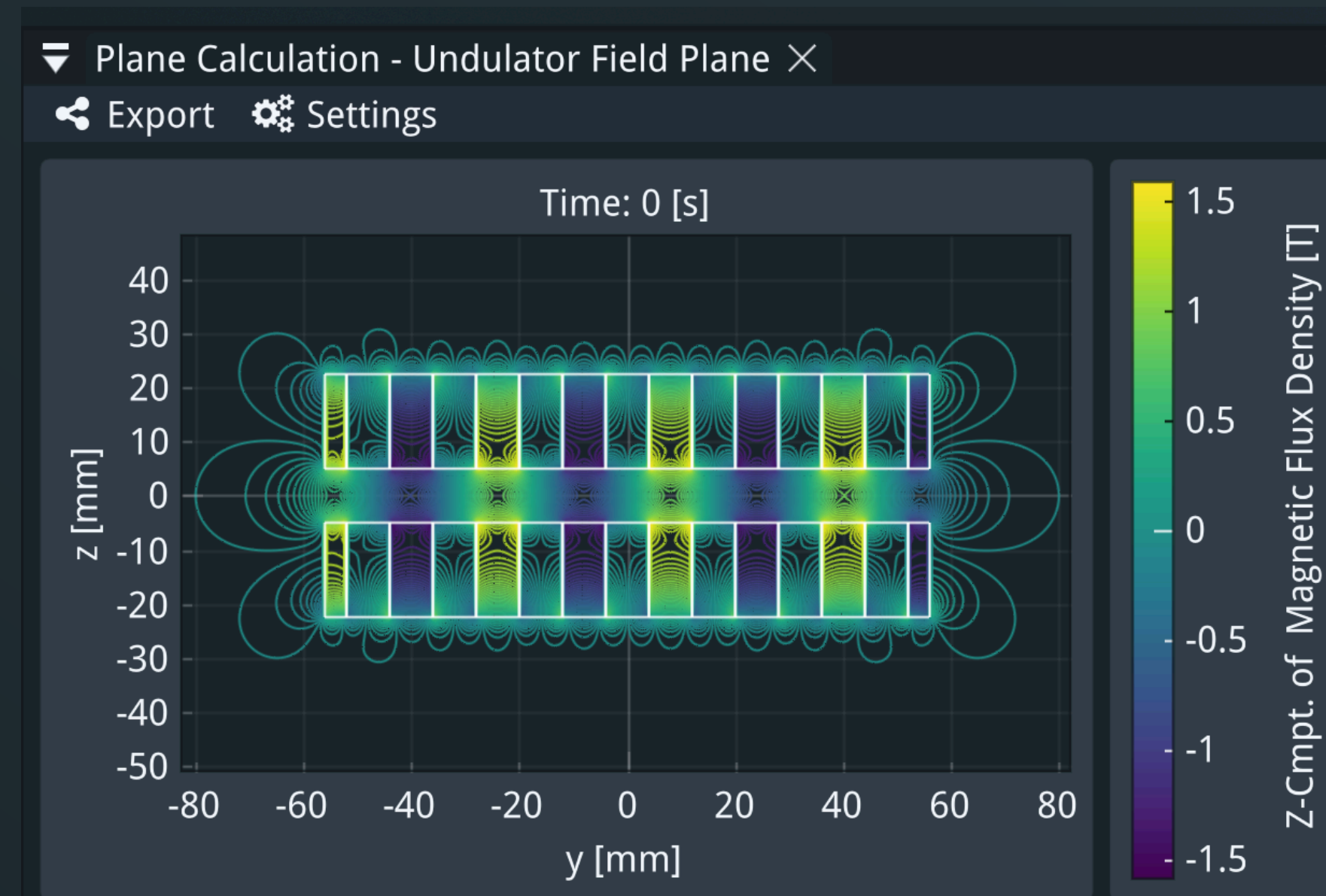
Magnetisation direction for the magnets



Simple undulator in Rat



Simple undulator in Radia



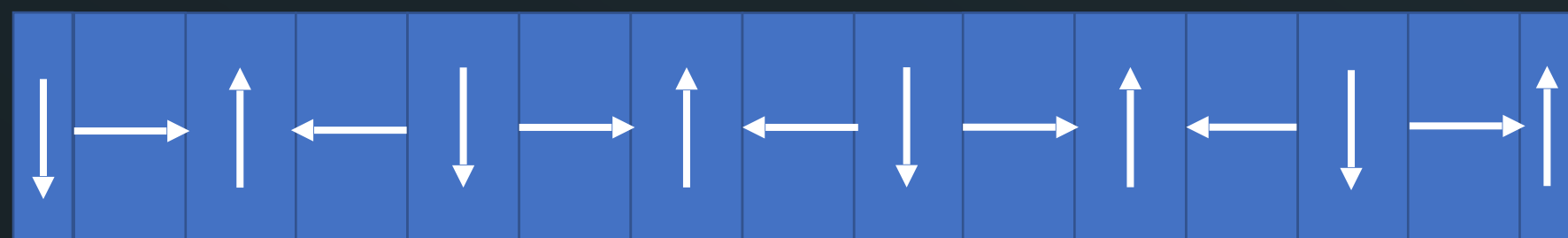
Magnetic field in planes (Rat)



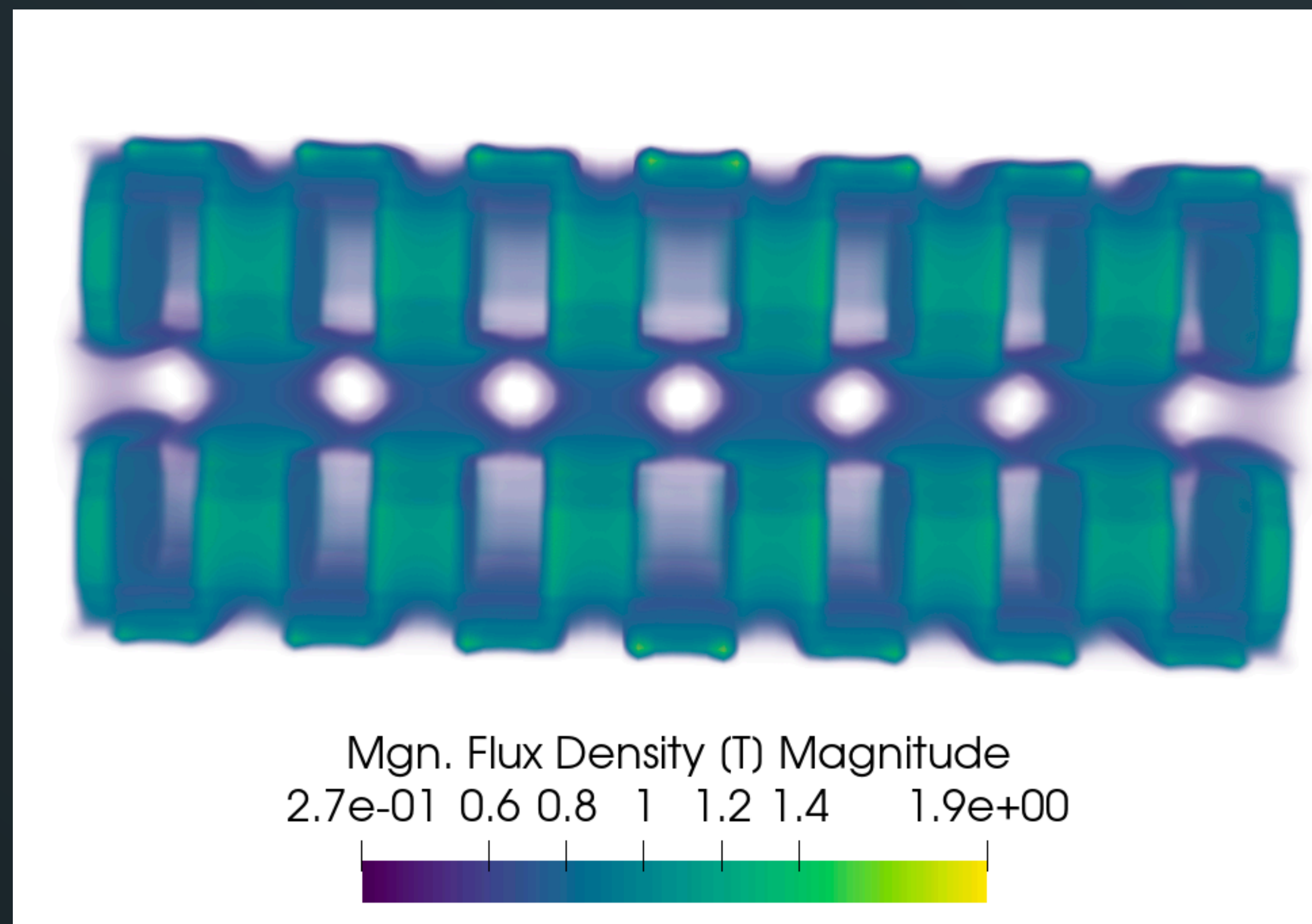
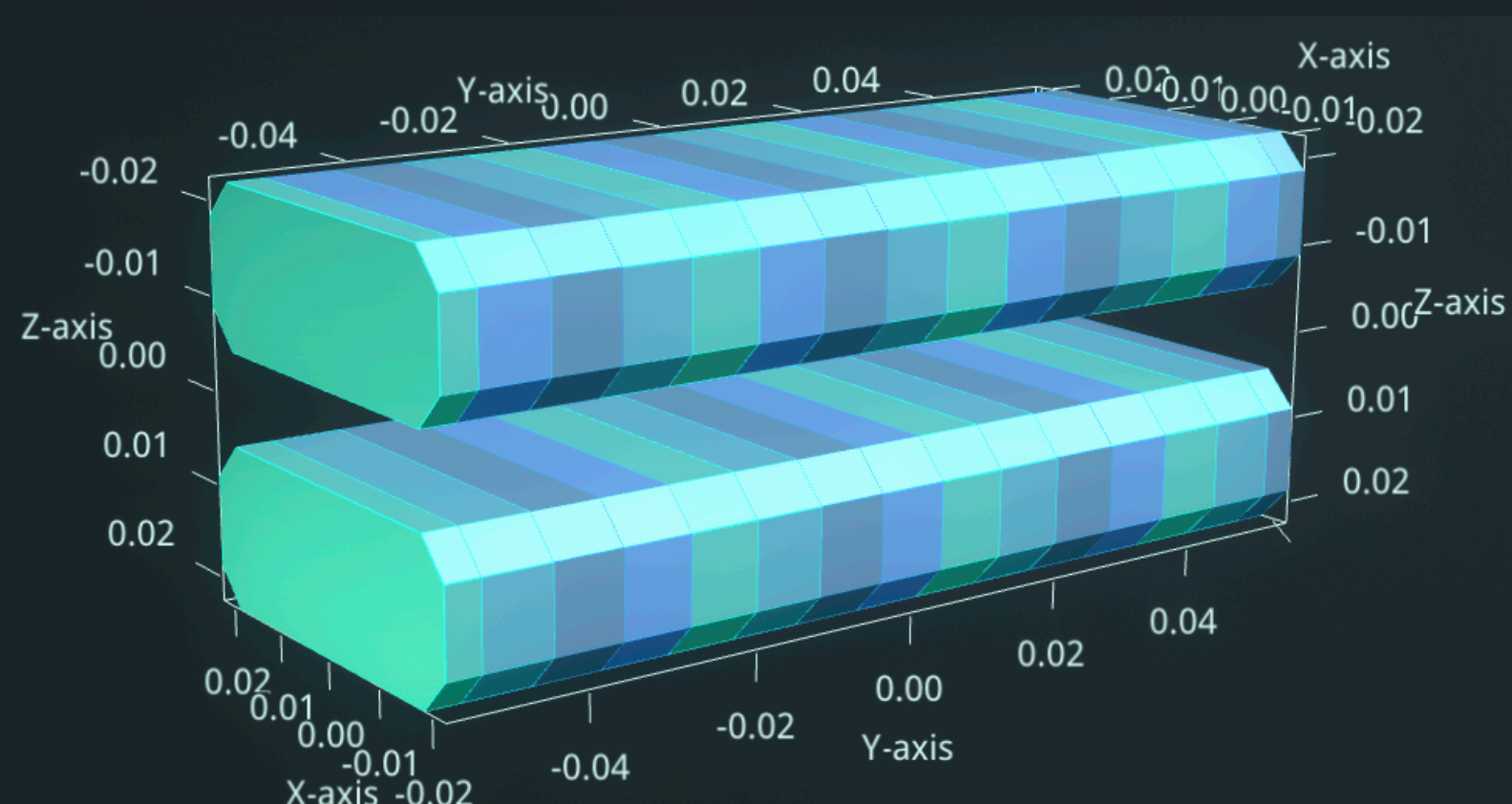
Validating Rat with a simple Undulator model

Repeat this for a simple undulator

- ▶ Reproduce the 3D shape in Rat, using Distmesh
- ▶ Set the magnetisation separately for each magnet
- ▶ Compare results to Radia simulation of the magnetic field



Magnetisation direction for the magnets



Magnetic field in 3D (Rat)



Summary

- ▶ Rat uses integral methods to solve different magnetic field calculation problems:
 - ▶ Biot-Savart with MLFMM
 - ▶ VIM for both iron and **now also permanent magnets**
- ▶ Rat includes many tools to quickly model magnets in 3D, and calculate their electro-magnetostatic properties
 - ▶ As well as quench, particle tracking, force density, etc